



This work is licensed under a [Creative Commons Attribution-NonCommercial-NoDerivatives 4.0 International License](https://creativecommons.org/licenses/by-nc-nd/4.0/).



2023. 06. 23



# Ice Shape Prediction Using ICEPAC

## 2nd AIAA ICE Prediction Workshop

Soonho Shon\*

Yonghwan Kim

Yu-Eop Kang

Younghyo Kim

Hansol Lee

Advisor : Prof. Kwanjung Yee



Seoul National University  
Department of aerospace engineering

**Aerospace Vehicle Design Laboratory**

# CONTENTS

I

**SIMULATION CODE DESCRIPTION**

II

**RESULTS & DISCUSSION**

III

**CONCLUSIONS**

# **SIMULATION CODE DESCRIPTION**

---

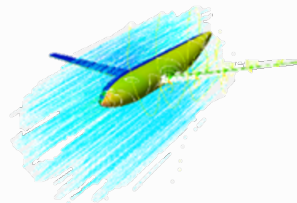
## Icing simulation code

- **ICEPAC (Ice Contour Evaluation and Performance Analysis Code)** developed by **Seoul National University** [1]
  - ✓ Consisting of four sequential modules based on **Eulerian method**

### Aerodynamic

➤ Calculate the **flow-field**

- Solve RANS equation
- Compute  $U_a, \rho_a, \tau_w, h_c$



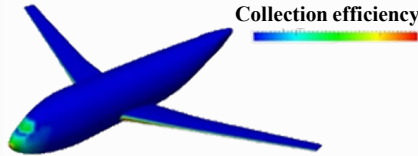
▲ Pressure contour

$\tau_w, Q_c$

### Droplet trajectory

➤ Determine the **droplet impingement rate**

- Solve droplet equation
- Compute  $U_d, \rho_d, \beta$



▲ Collection efficiency  $\beta$  contour

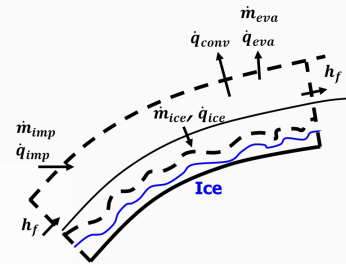
$U_a, \rho_a$

$U_d, \beta$

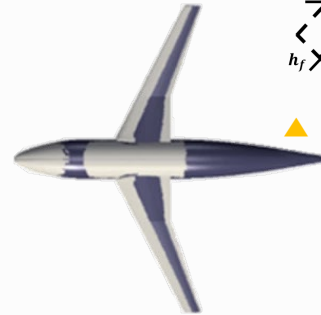
### Thermodynamic

➤ Determine the **ice accretion rate**

- Solve SWIM equation
- Compute  $h_f, \dot{m}_{ice}$



▲ Schematic view of SWIM



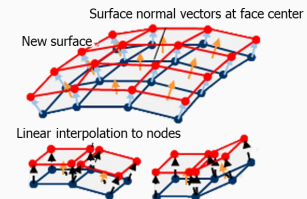
▲  $\dot{m}_{ice}$  distribution on the surface

$\dot{m}_{ice}$

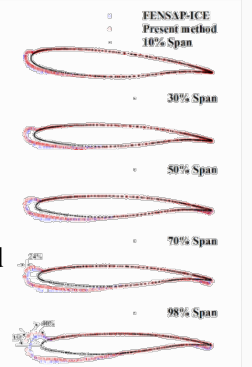
### Ice Growth

➤ Update the geometry change due to icing

- Compute Ice growth based on  $\dot{m}_{ice}$



▲ Surface generation method



▲ Airfoil ice shape generation

Quasai-steady assumption n times iteration

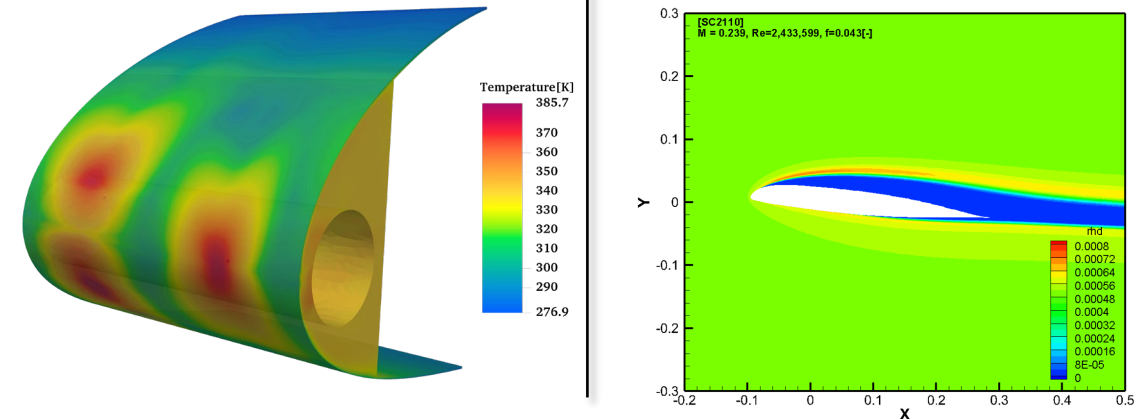
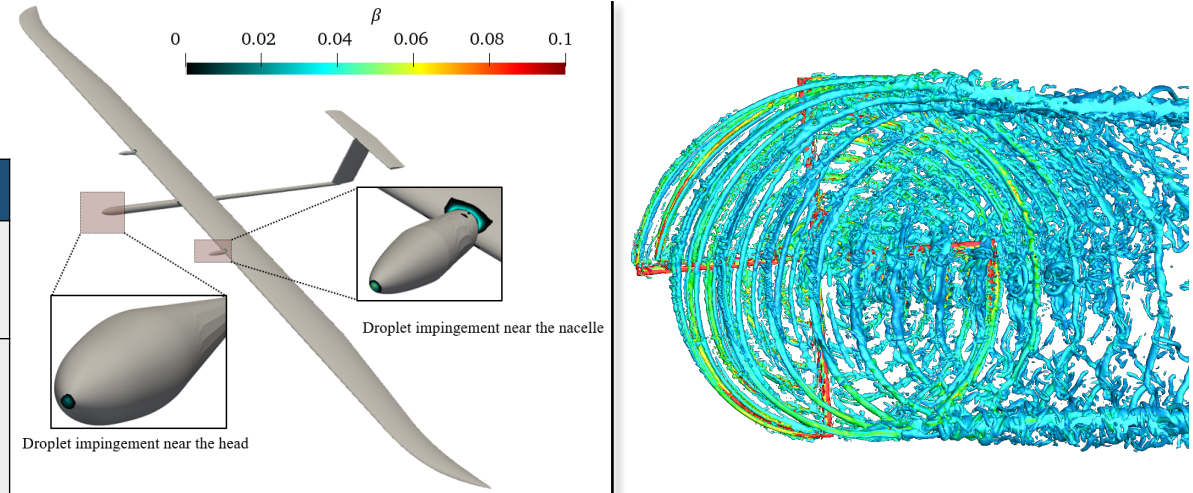
## ■ Icing simulation code

- **ICEPAC (Ice Contour Evaluation and Performance Analysis Code)** developed by **Seoul National University**

- ✓ Based on both structured and unstructured mesh

- **OpenFOAM** (Unstructured) and **KFLOW** [2, 3] (Structured)

Codes	OpenFOAM	KFLOW
Grid types	<ul style="list-style-type: none"> <li>• Unstructured 2D/3D</li> </ul>	<ul style="list-style-type: none"> <li>• Structured 2D/3D</li> </ul>
Flow	<ul style="list-style-type: none"> <li>• RANS → Upwind 2<sup>nd</sup> order → <math>SA, \gamma - Re_{\theta}</math> transition, etc.</li> <li>• Roughness model → Fortin's ESGR model<sup>[4]</sup></li> </ul>	<ul style="list-style-type: none"> <li>• RANS → Roe's FDS / HLLC+ / AUSMPW+ → <math>SA, \gamma - Re_{\theta}</math> transition, etc.</li> <li>• Roughness model → Fortin's ESGR model</li> </ul>
Droplet	<ul style="list-style-type: none"> <li>• 2D/3D Eulerian → Upwind 1<sup>st</sup> order</li> </ul>	<ul style="list-style-type: none"> <li>• 2D/3D Eulerian → HLLC 2<sup>nd</sup> order</li> </ul>
Thermo.	<ul style="list-style-type: none"> <li>• SWIM</li> </ul>	<ul style="list-style-type: none"> <li>• SWIM</li> </ul>
Application	<ul style="list-style-type: none"> <li>• Icing on complex geometry</li> <li>• Anti-icing</li> </ul>	<ul style="list-style-type: none"> <li>• Rotor icing</li> <li>• Oscillating airfoil</li> </ul>



▲ Simulation analysis approach

# **RESULTS & DISCUSSION**

---



# RESULTS & DISCUSSION

## ■ Case 1 & 2 : CRM-65 hybrid (3D)



Case 1: CRM-65 Mid-span Hybrid (3D)



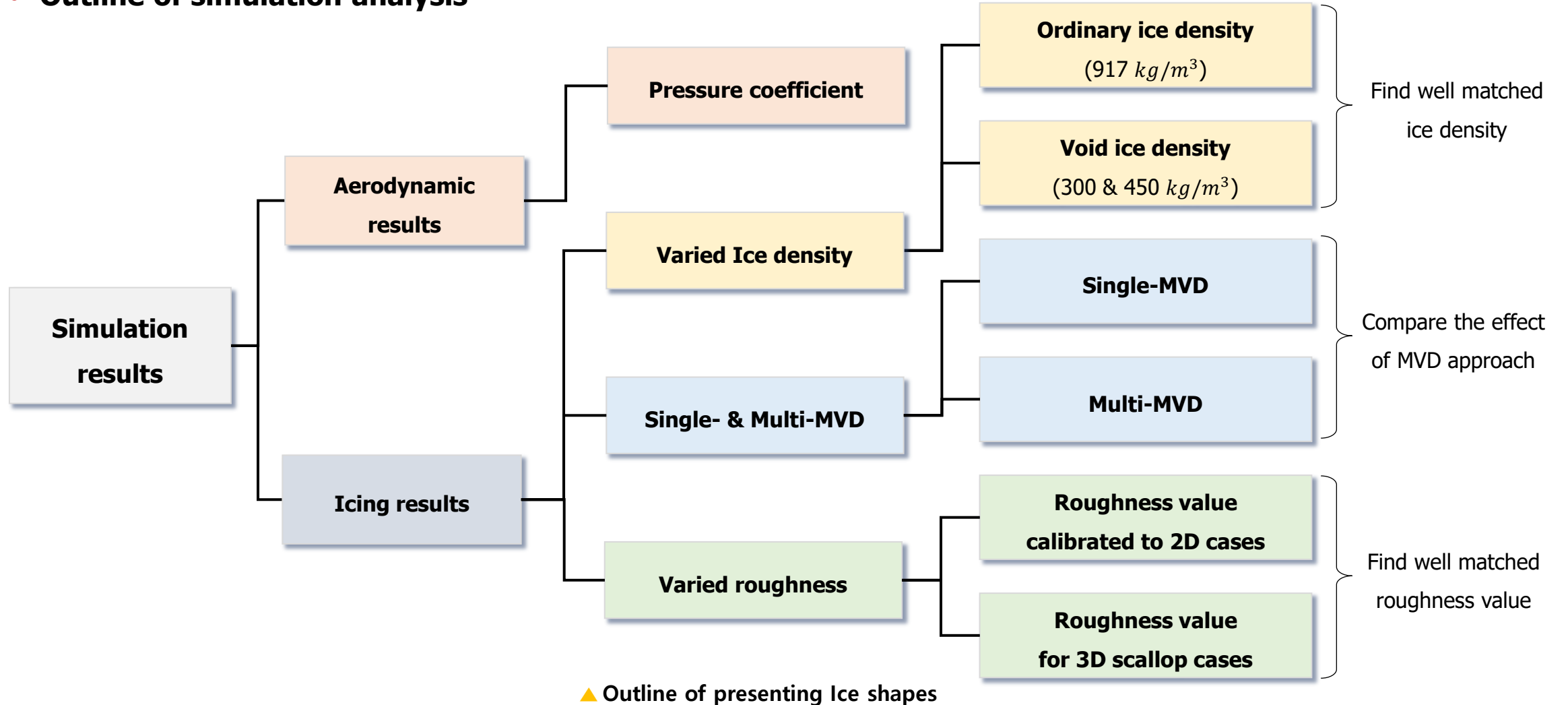
Case 2: CRM-65 Inboard Hybrid (3D)



# RESULTS & DISCUSSION

## ■ Case 1 & 2 : CRM-65 hybrid (3D)

- Outline of simulation analysis



# RESULTS & DISCUSSION

## ■ Case 1 & 2 : CRM-65 hybrid (3D)

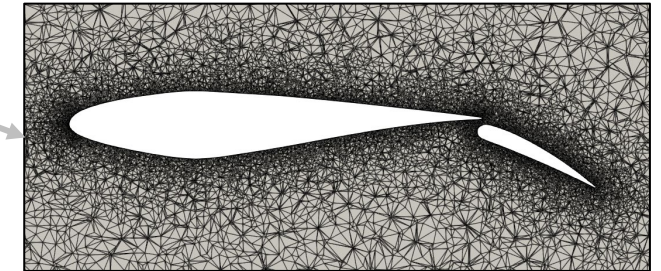
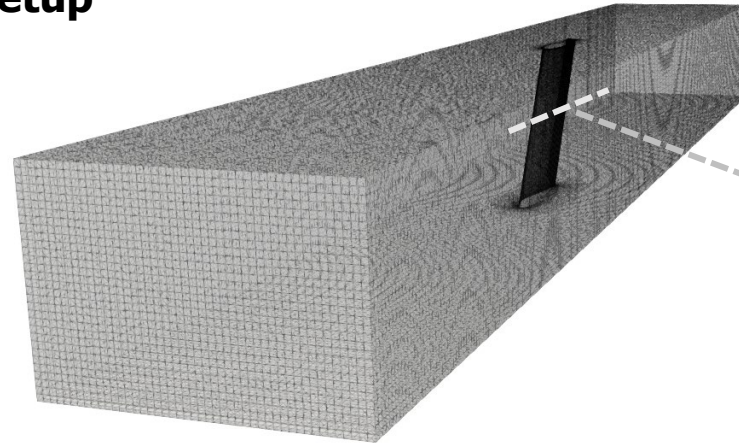
### ● Computational grid and numerical setup

#### ✓ Computational grid

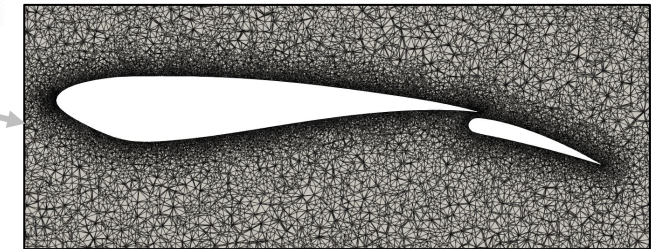
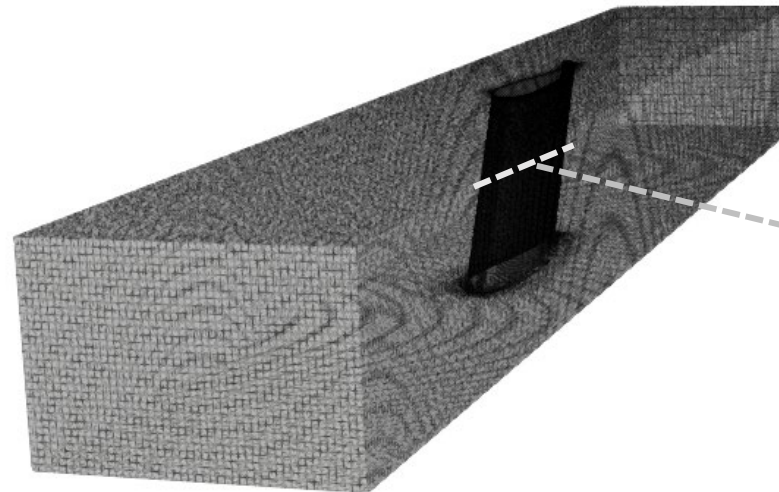
- Using no-gap configuration
- **Unstructured mesh**
  - **Composed of 12 million volume cells**
  - $y^+=1$  at wall

#### ✓ Numerical setup

- Spatial Discretization
  - Upwind 2<sup>nd</sup> order
- Temporal Integration
  - PIMPLE algorithm
- Turbulence model
  - Modified SA model
- Roughness model
  - Fortin's ESGR model



▲ Grid configuration of Mid-span hybrid wing



▲ Grid configuration of Inboard hybrid wing

# RESULTS & DISCUSSION

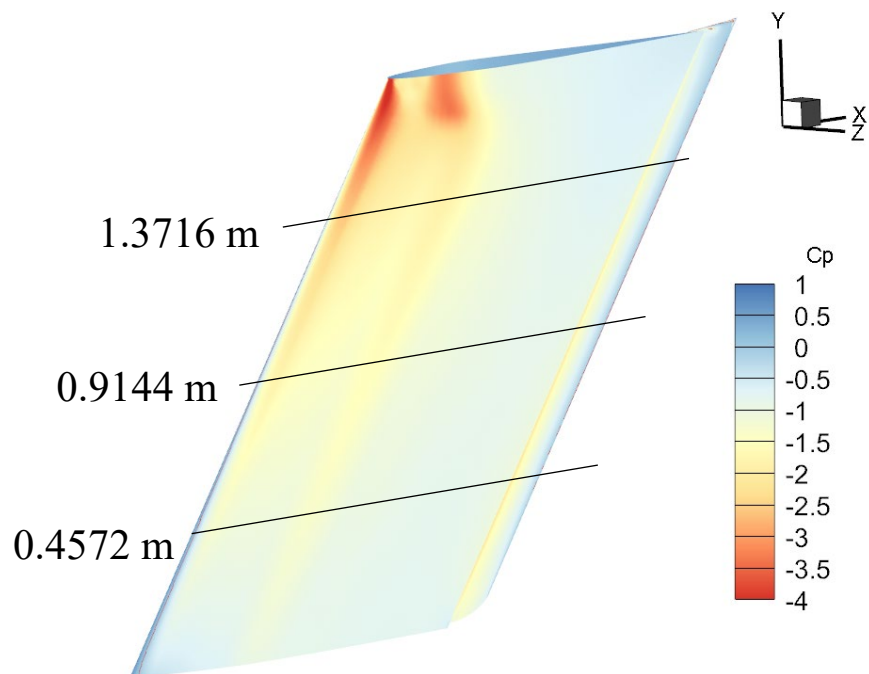
## ■ Case 1 & 2 : CRM-65 hybrid (3D)

### • Aerodynamic results of Mid-span case

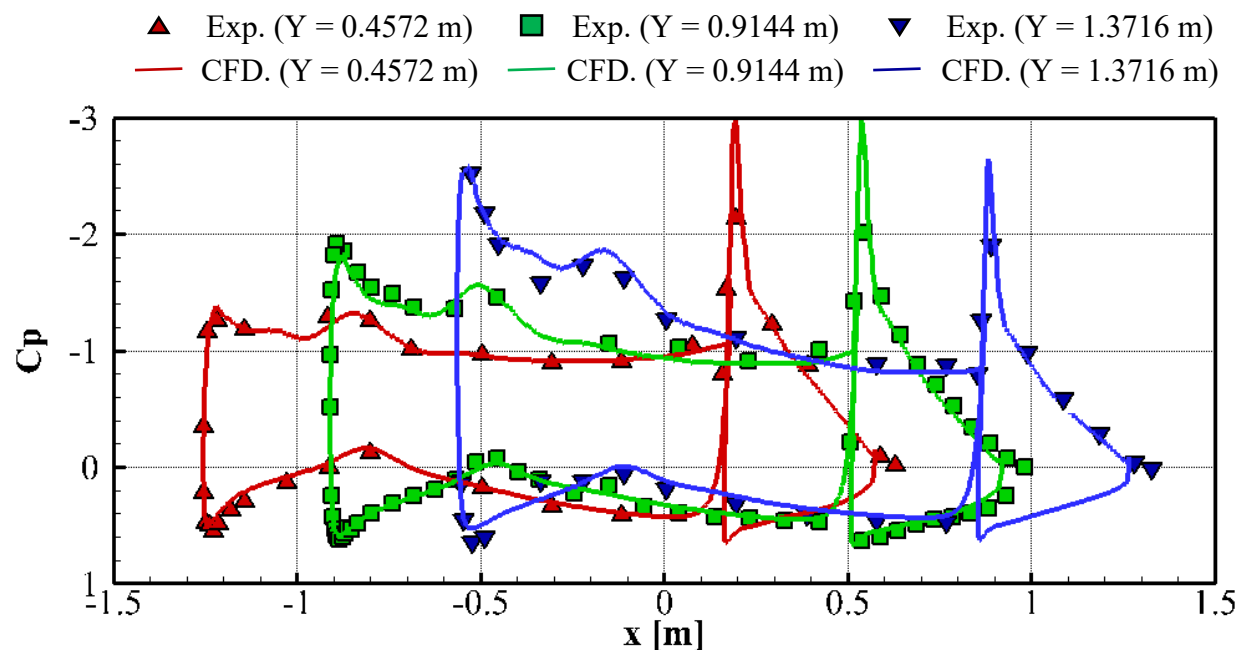
✓ Pressure coefficient comparison between experiment and simulation

- Good agreement with experimental results
  - Especially on the centerline ( $y = 0.9144\text{m}$ ), the main region of interest of the model

Speed (m/s)	$T_{static}$ (°C)	MVD ( $\mu\text{m}$ )	LWC ( $\text{g}/\text{m}^3$ )	Time (min.)
66.9	-3.6	25	1.0	29.0



▲ Surface pressure contours



▲ Pressure coefficient comparison between experiment and simulation

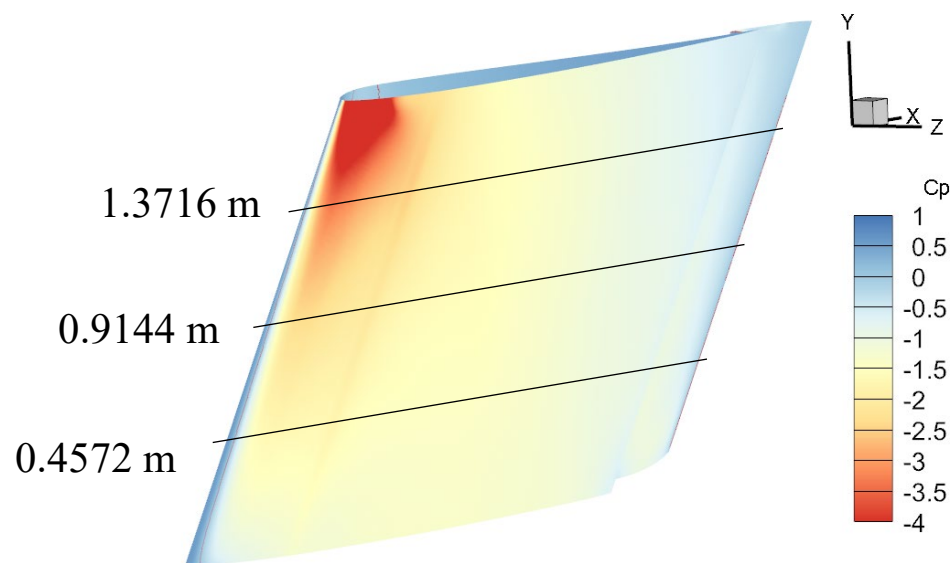
# RESULTS & DISCUSSION

## Case 1 & 2 : CRM-65 hybrid (3D)

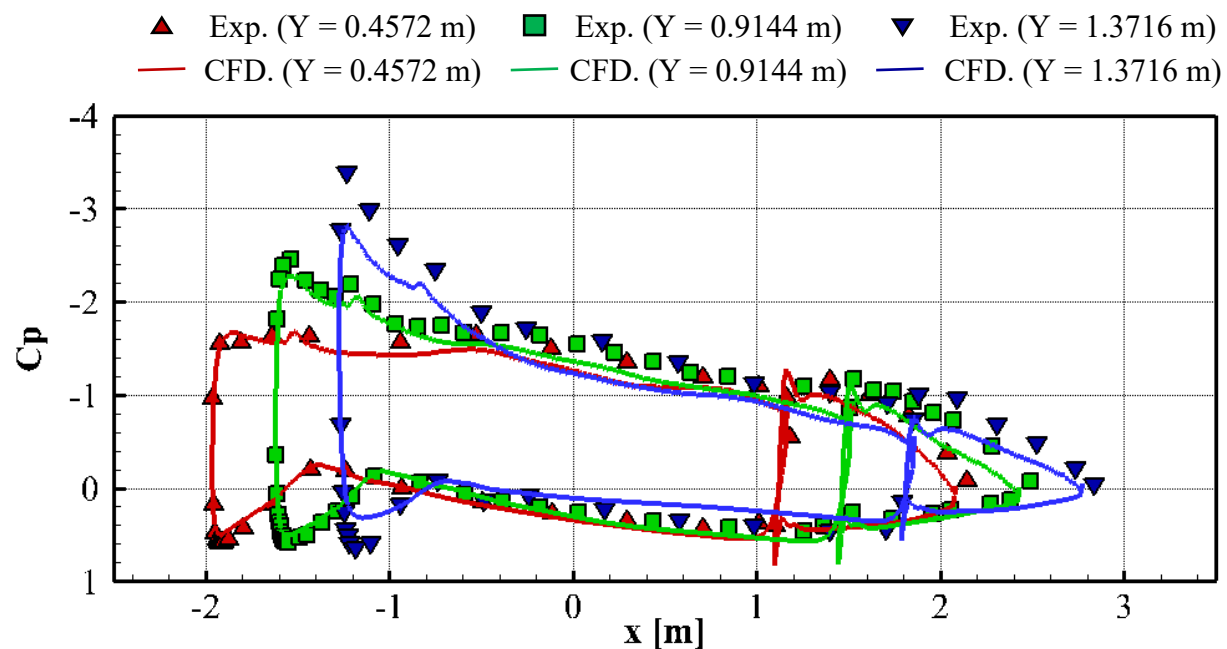
### Aerodynamic results of Inboard case

- ✓ Pressure coefficient comparison between experiment and simulation
  - Good agreement with experimental results
    - Especially on the centerline ( $y = 0.9144\text{m}$ ), the main region of interest of the model

Speed (m/s)	$T_{static}$ ( $^{\circ}\text{C}$ )	MVD ( $\mu\text{m}$ )	LWC ( $\text{g}/\text{m}^3$ )	Time (min.)
66.9	-3.6	25	1.0	29.0



▲ Surface pressure contours



▲ Pressure coefficient comparison between experiment and simulation

## Case 1 & 2 : CRM-65 hybrid (3D)

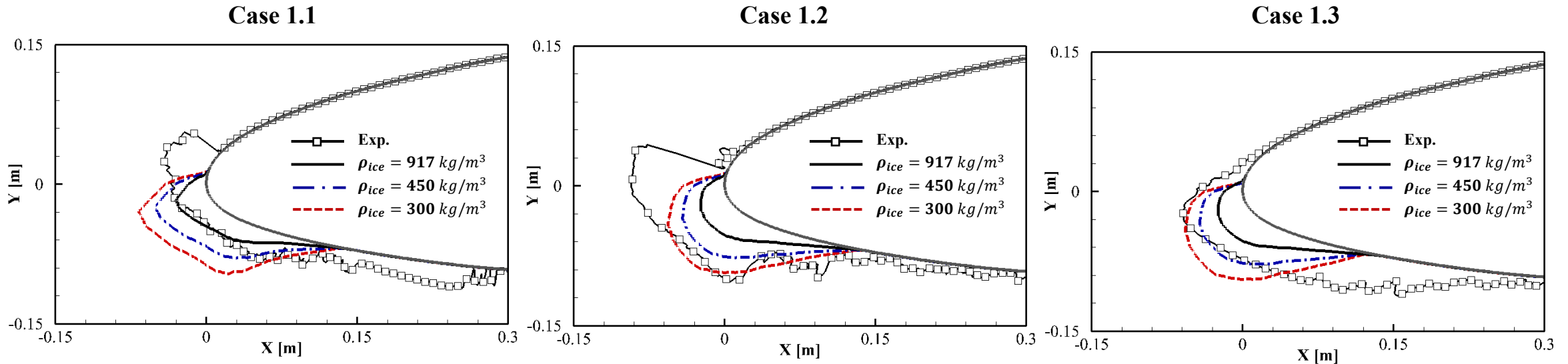
### Icing results

#### Comparison of ice density for Mid-span cases

- Ordinary ice density
  - $917 \text{ kg/m}^3$
- Void ice density
  - Constant density was adopted
  - $\rho_{ice} = 300 \text{ and } 450 \text{ kg/m}^3$  (Density range is refer to paper [4])

➤  **$300 \text{ kg/m}^3$  of ice density is set for the largest scallop case**, and  $450 \text{ kg/m}^3$  for the rest

Single MVD / 2D roughness value					
Case No.	Speed (m/s)	$T_{static}$ (°C)	MVD ( $\mu\text{m}$ )	LWC ( $\text{g/m}^3$ )	Time (min.)
1.1	66.9	-3.6	25	1.0	29.0
1.2	66.9	-8.5	25	1.0	29.0
1.3	66.9	-26.0	25	1.0	29.0



▲ Ice shape comparison between experiment and simulation (Mid-span chord length = 1.894 m)



## ■ Case 1 & 2 : CRM-65 hybrid (3D)

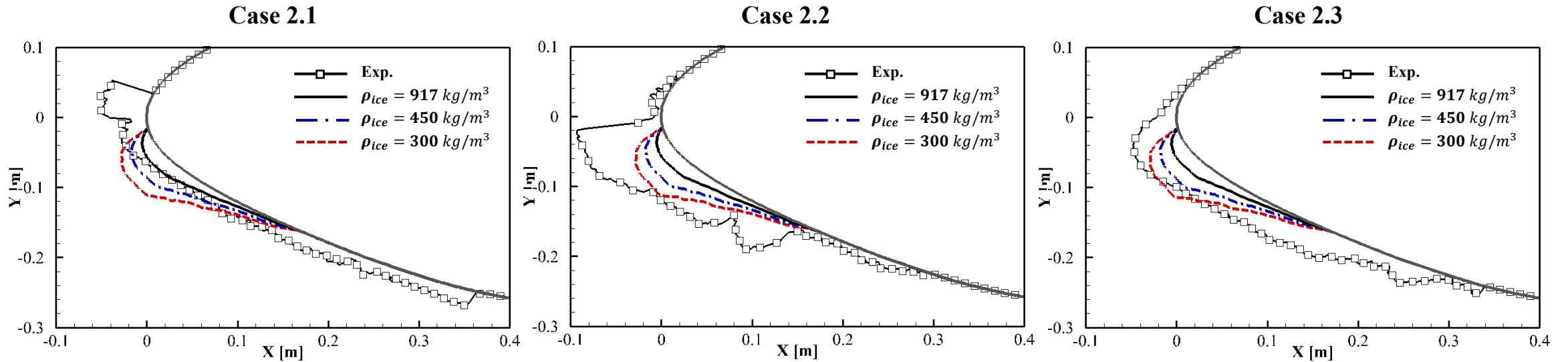
### • Icing results

#### ✓ Comparison of **ice density** for Inboard cases

- Ordinary ice density
  - $917 \text{ kg/m}^3$
- Void ice density
  - Constant density was adopted
  - $\rho_{ice} = 300 \text{ and } 450 \text{ kg/m}^3$  (Density range is refer to paper [4])

➤  **$300 \text{ kg/m}^3$  of ice density is set for the largest scallop case**, and  $450 \text{ kg/m}^3$  for the rest

Single MVD / 2D roughness value					
Case No.	Speed (m/s)	$T_{static}$ (°C)	MVD ( $\mu\text{m}$ )	LWC ( $\text{g/m}^3$ )	Time (min.)
2.1	66.9	-3.6	25	1.0	29.0
2.2	66.9	-8.5	25	1.0	29.0
2.3	66.9	-26.0	25	1.0	29.0



▲ Ice shape comparison between experiment and simulation (Inboard chord length = 4.11 m)

# RESULTS & DISCUSSION

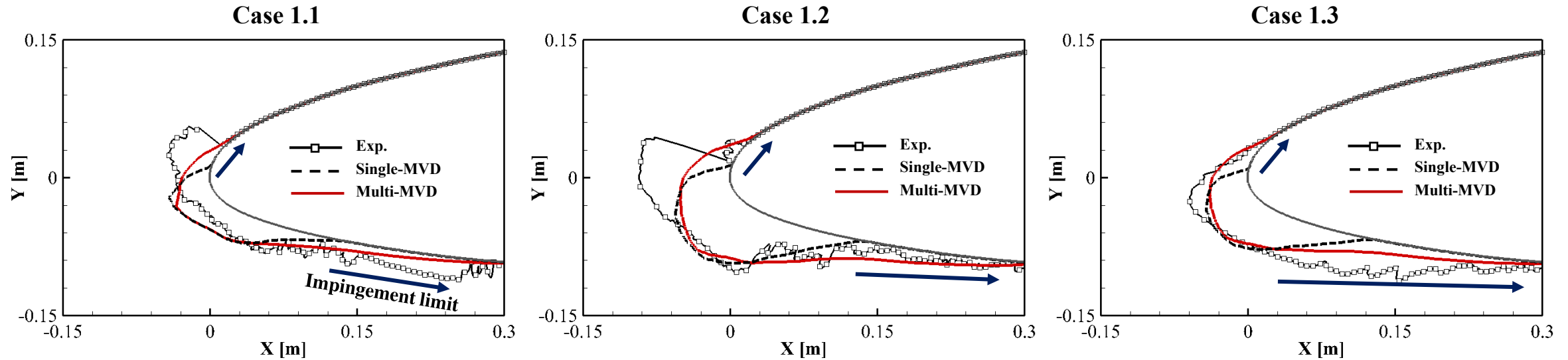
## Case 1 & 2 : CRM-65 hybrid (3D)

### Icing results

#### Comparison of **MVD approach** for Mid-span cases

- Single MVD
  - 25  $\mu\text{m}$
- Multi-MVD based on IRT droplet distribution
  - 7.3, 9.9, 13.7, 24.9, 44.9, 74.9, and 127.6  $\mu\text{m}$
- **Multi-MVD** has much **better agreement of impingement limit**
  - Multi-MVD approach will be used

Multi MVD / 2D roughness value						
Case No.	Speed (m/s)	$T_{static}$ ( $^{\circ}\text{C}$ )	MVD ( $\mu\text{m}$ )	LWC ( $\text{g}/\text{m}^3$ )	Time (min.)	Void density ( $\text{kg}/\text{m}^3$ )
1.1	66.9	-3.6	25	1.0	29.0	450
1.2	66.9	-8.5	25	1.0	29.0	300
1.3	66.9	-26.0	25	1.0	29.0	450



▲ Ice shape comparison between experiment and simulation (Mid-span chord length = 1.894 m)



# RESULTS & DISCUSSION

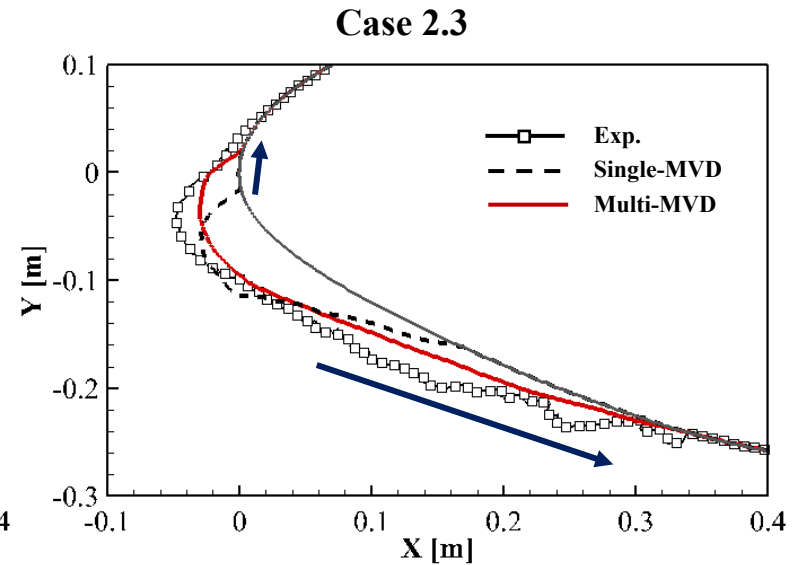
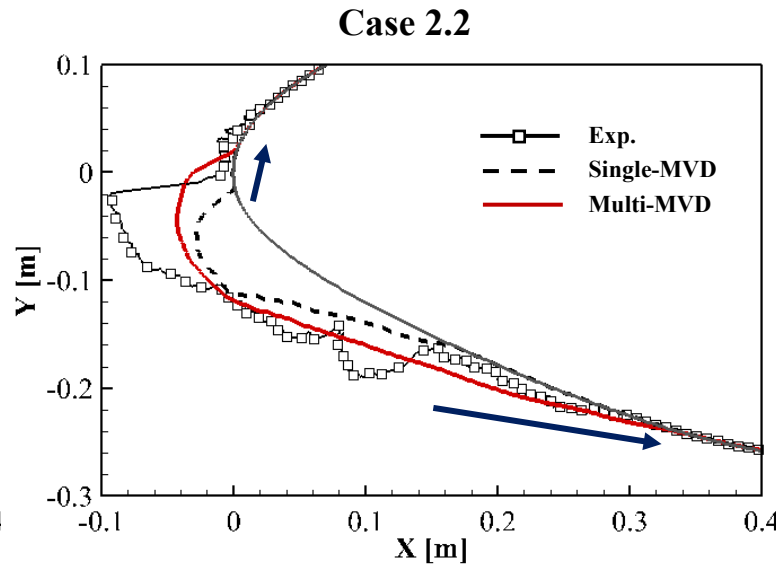
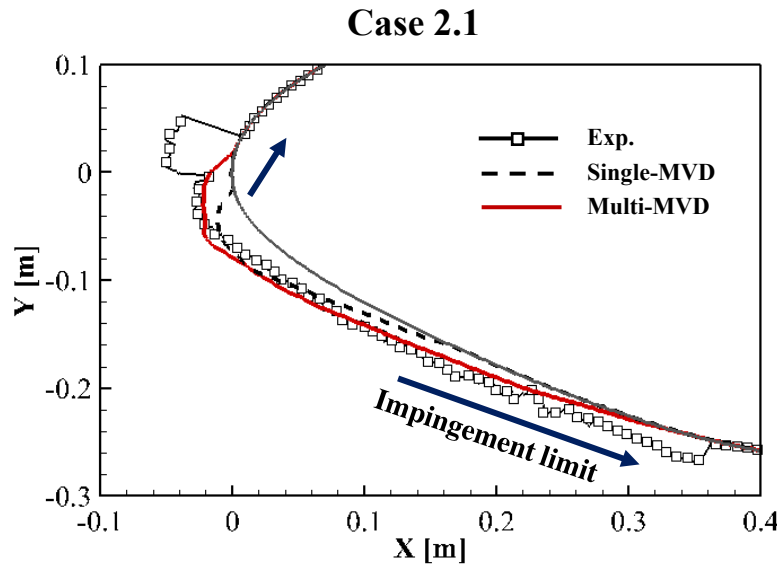
## ■ Case 1 & 2 : CRM-65 hybrid (3D)

### • Icing results

#### ✓ Comparison of **MVD approach** for Inboard cases

- Single MVD
  - 25  $\mu\text{m}$
- Multi-MVD based on IRT droplet distribution
  - 7.3, 9.9, 13.7, 24.9, 44.9, 74.9, and 127.6  $\mu\text{m}$
- **Multi-MVD** has much **better agreement of impingement limit**
  - Multi-MVD approach will be used

Multi MVD / 2D roughness value						
Case No.	Speed (m/s)	$T_{static}$ ( $^{\circ}\text{C}$ )	MVD ( $\mu\text{m}$ )	LWC ( $\text{g}/\text{m}^3$ )	Time (min.)	Void density ( $\text{kg}/\text{m}^3$ )
2.1	66.9	-3.6	25	1.0	29.0	450
2.2	66.9	-8.5	25	1.0	29.0	300
2.3	66.9	-26.0	25	1.0	29.0	450



▲ Ice shape comparison between experiment and simulation (Inboard chord length = 4.11 m)

## ■ Case 1 & 2 : CRM-65 hybrid (3D)

### • Icing results

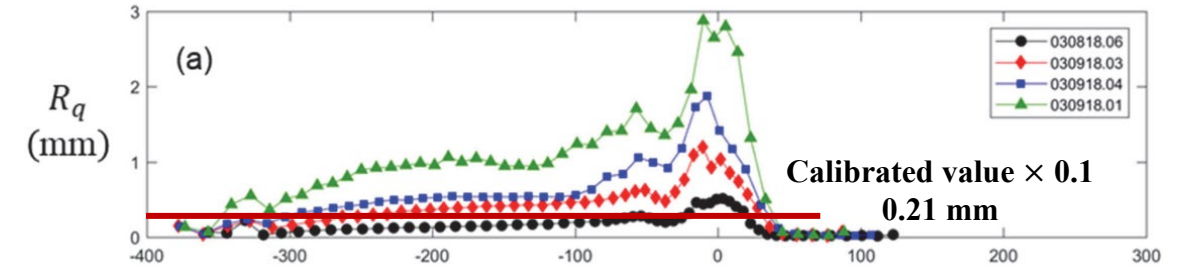
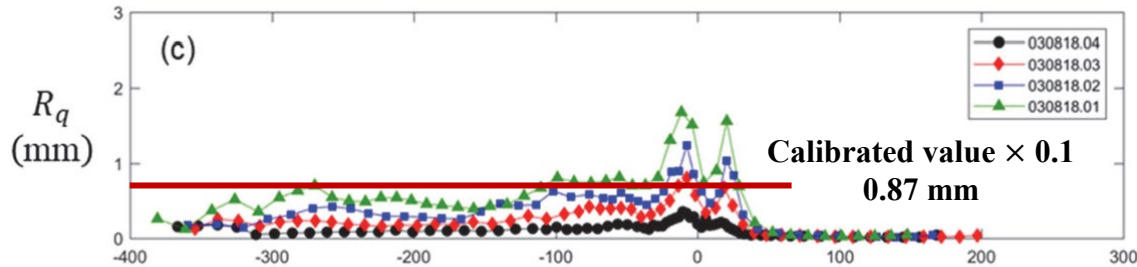
#### ✓ Necessity of **different roughness value** for scallop cases

- **Different physical mechanism** between scallops and water film model
  - **Not describing feather formation and scallop** in simulation → **lower ice horn angle**
- Larger calibrated roughness values to 2D cases than experimental values [5]

} **Need to use lower roughness value**  
to describe ice horn angle of the scallop cases

#### ✓ Three different roughness values are compared

- Roughness value calibrated to 2D cases (*Calibrated  $k_s$  (2D)*)
- *Calibrated  $k_s$  (2D)*  $\times 0.1$  → Usually used for 3D scallop cases in ICEPAC
- *Calibrated  $k_s$  (2D)*  $\times 0.01$



▲ Calibrated value experimental roughness value of Mid-span case (Case 1) [5]

▲ Calibrated value experimental roughness value of Mid-span (Case 2) [5]

# RESULTS & DISCUSSION

## Case 1 & 2 : CRM-65 hybrid (3D)

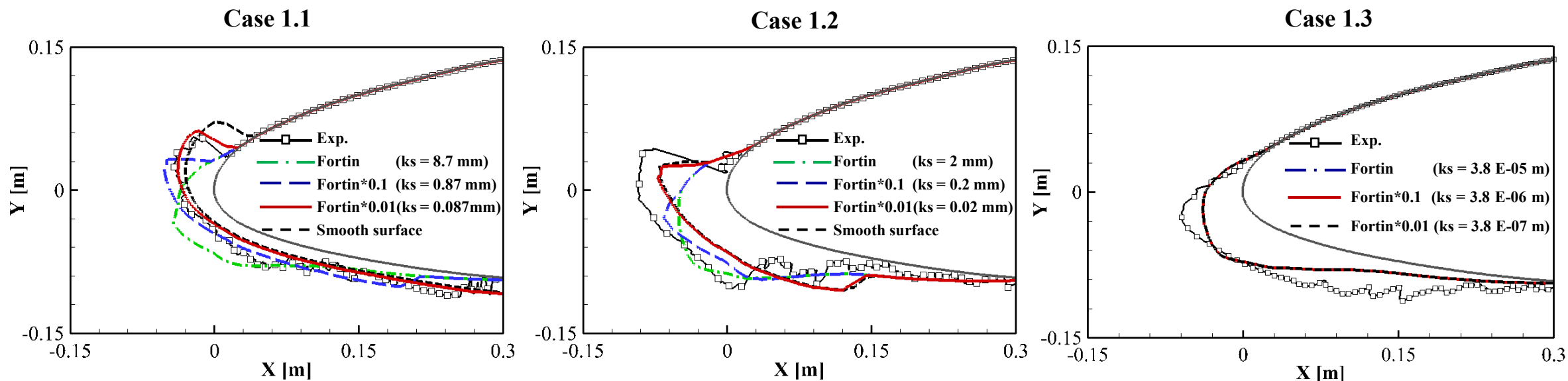
### Icing results

✓ Comparison of **varied roughness value** for Mid-span cases

- Roughness value calibrated to 2D cases
  - *Calibrated  $k_s$  (2D)*
- Roughness value for 3D scallop cases
  - *Calibrated  $k_s$  (2D) × 0.1*
  - *Calibrated  $k_s$  (2D) × 0.01* → Best agreement in hybrid wing case

➤ **Roughness values smaller than calibrated values has better agreement**

Multi MVD / Varied roughness value						
Case No.	Speed (m/s)	$T_{static}$ (°C)	MVD ( $\mu\text{m}$ )	LWC ( $\text{g}/\text{m}^3$ )	Time (min.)	Void density ( $\text{kg}/\text{m}^3$ )
1.1	66.9	-3.6	25	1.0	29.0	450
1.2	66.9	-8.5	25	1.0	29.0	300
1.3	66.9	-26.0	25	1.0	29.0	450



▲ Ice shape comparison between experiment and simulation (Mid-span chord length = 1.894 m)

# RESULTS & DISCUSSION

## ■ Case 1 & 2 : CRM-65 hybrid (3D)

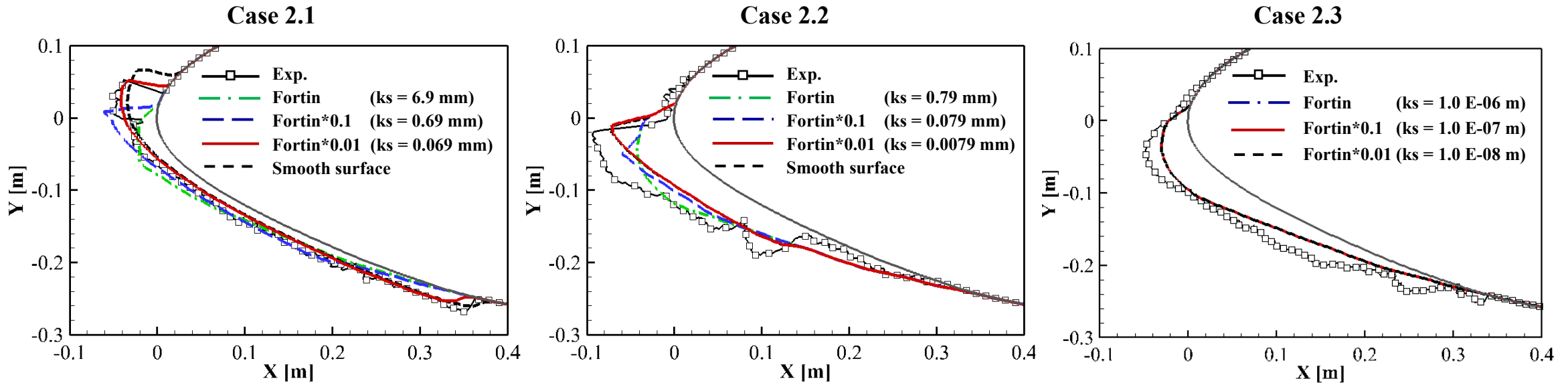
### • Icing results

✓ Comparison of **varied roughness value** for Inboard cases

- Roughness value calibrated to 2D cases
  - *Calibrated  $k_s$  (2D)*
- Roughness value for 3D scallop cases
  - *Calibrated  $k_s$  (2D) × 0.1*
  - *Calibrated  $k_s$  (2D) × 0.01* → Best agreement in hybrid wing case

➤ **Roughness values smaller than calibrated values has better agreement**

Multi MVD / Varied roughness value						
Case No.	Speed (m/s)	$T_{static}$ (°C)	MVD ( $\mu\text{m}$ )	LWC ( $\text{g}/\text{m}^3$ )	Time (min.)	Void density ( $\text{kg}/\text{m}^3$ )
2.1	66.9	-3.6	25	1.0	29.0	450
2.2	66.9	-8.5	25	1.0	29.0	300
2.3	66.9	-26.0	25	1.0	29.0	450



▲ Ice shape comparison between experiment and simulation (Inboard chord length = 4.11 m)

# RESULTS & DISCUSSION

## ■ Case 3 : RG-15 low speed Icing

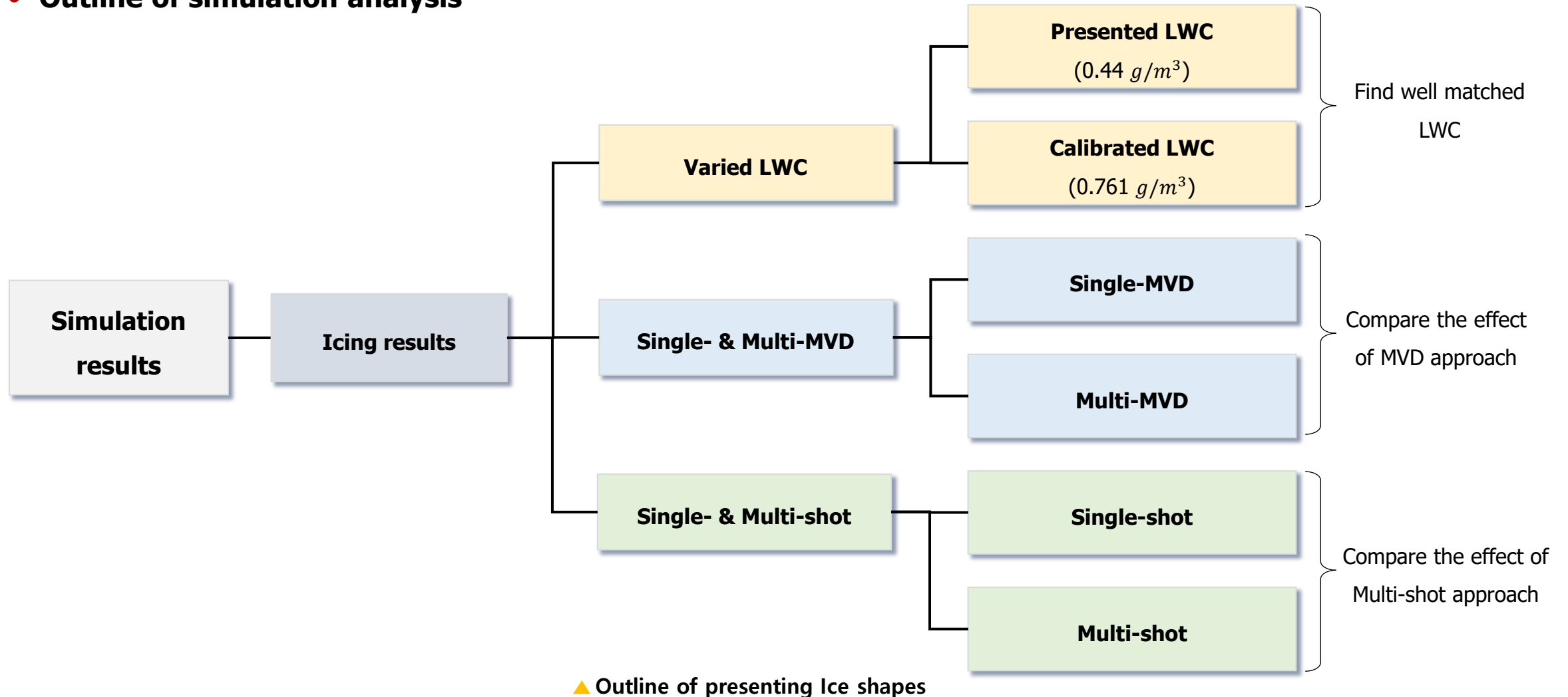


Case 3: RG-15 Low Speed Icing

# RESULTS & DISCUSSION

## ■ Case 3 : RG-15 low speed Icing

- Outline of simulation analysis



# RESULTS & DISCUSSION

## ■ Case 3 : RG-15 low speed Icing

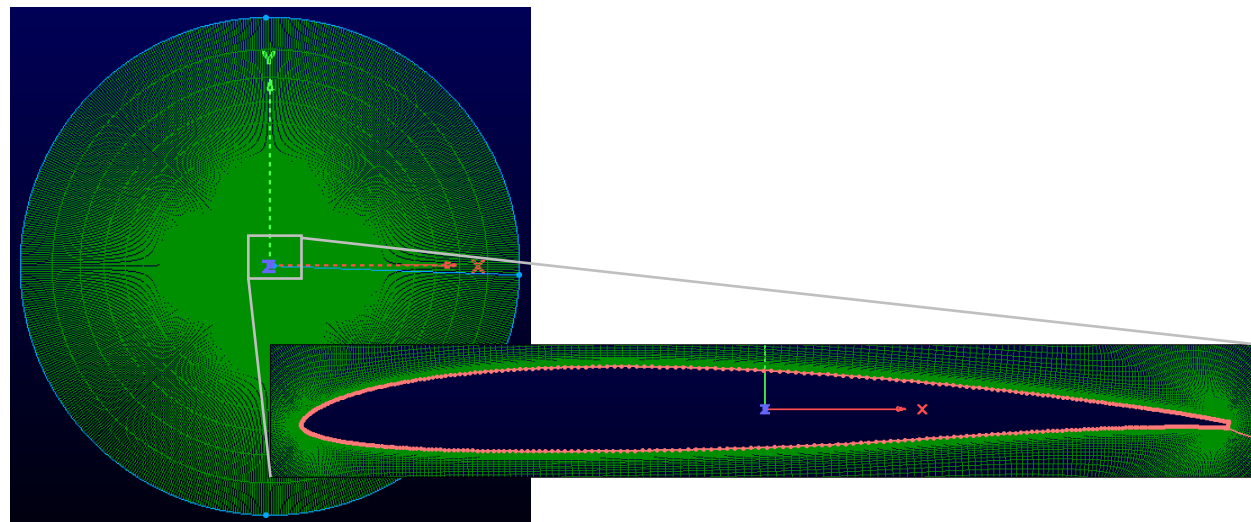
### • Computational grid and numerical setup

#### ✓ Computational grid

- O-type grid
  - Composed of 53,416 volume cells
  - $y^+=1$  at wall

#### ✓ Numerical setup

- Spatial Discretization
  - Upwind 2<sup>nd</sup> order
- Temporal Integration
  - PIMPLE algorithm
- Turbulence model
  - $Re_\theta - \gamma$  turbulence model
- Roughness model
  - Fortin's ESGR model



▲ O-type grid of RG-15

Domain boundary	Aerodynamic boundary condition	Droplet boundary condition
Inlet	Velocity inlet, 25 m/s	Velocity inlet, 25 m/s
Outlet	ZeroGradient	ZeroGradient
Model walls	No-slip wall (Isothermal)	ZeroGradient



# RESULTS & DISCUSSION

## ■ Case 3 : RG-15 low speed Icing

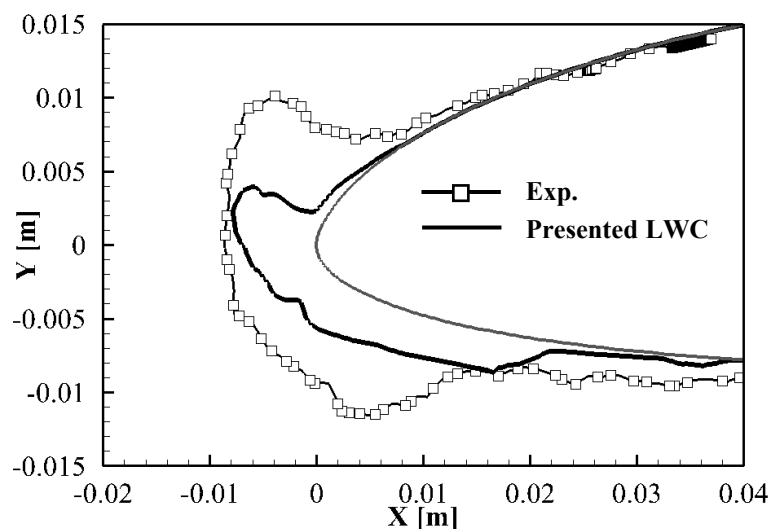
### • Icing results

✓ Ice shapes of presented LWC (from workshop)

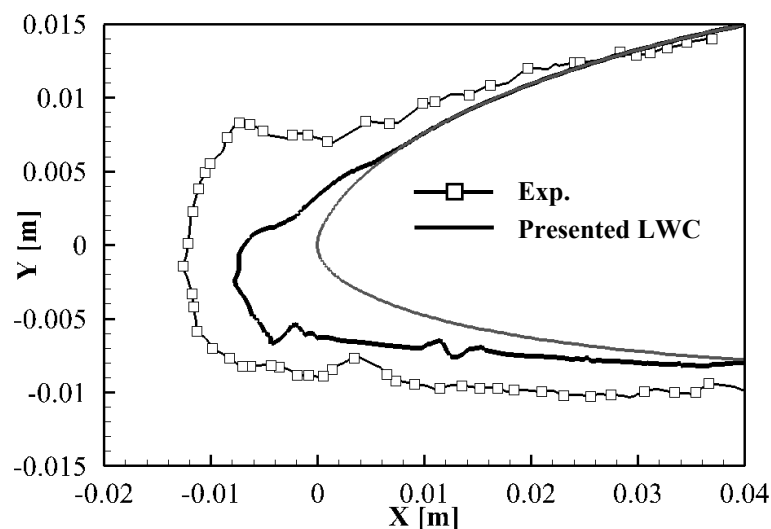
- **Smaller ice shapes** than ice shape of experiment
- Large mass difference → No mass conservation

Case	Speed (m/s)	AoA (deg.)	$T_{static}$ (°C)	MVD ( $\mu\text{m}$ )	LWC ( $\text{g}/\text{m}^3$ )	Time (min.)
3.1	25	4	-4	23	<b>0.44</b>	20
3.2	25	4	-4	23	<b>0.44</b>	20
3.3	25	4	-10	23	<b>0.44</b>	20

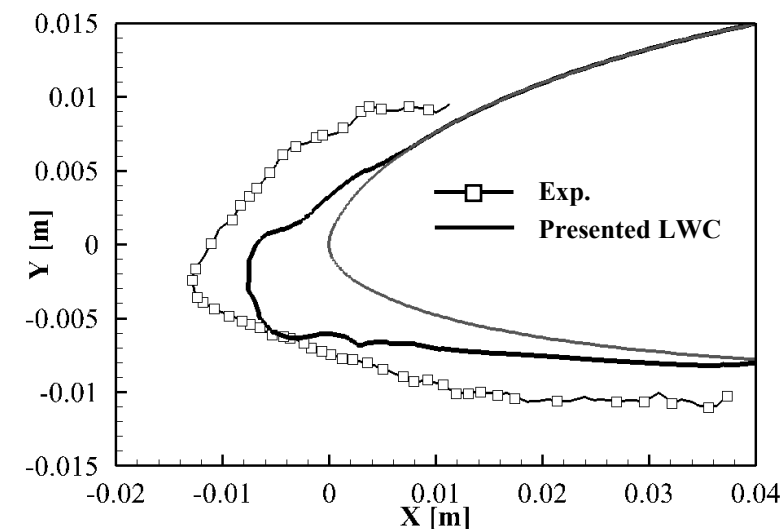
Case 3.1



Case 3.2



Case 3.3



▲ Ice shape comparison between experiment and simulation

## ■ Case 3 : RG-15 low speed Icing

### • Icing results

✓ Considering **uncertainty of LWC**

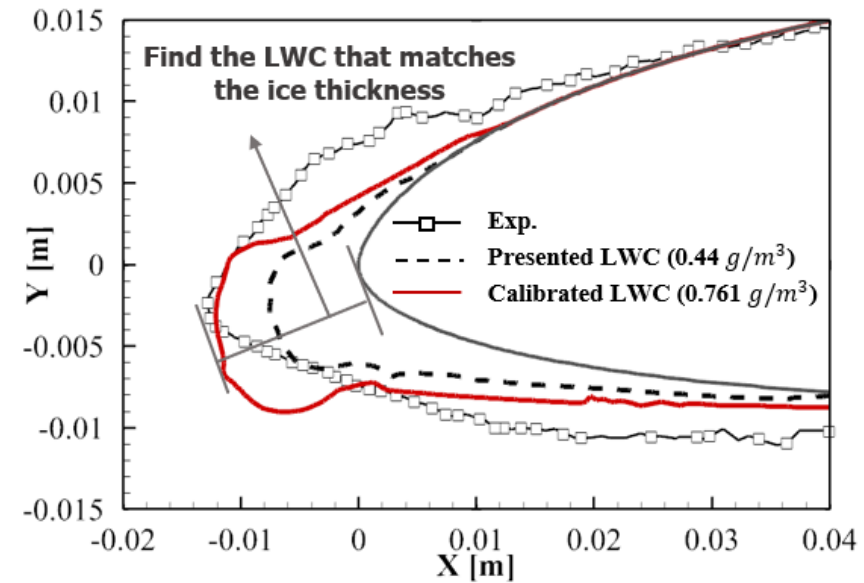
- **The measured LWC by instruments differ** by almost a factor of two
  - ICEMET : 0.42 ~0.48 / CDP (DTU & FMI) : 0.74 ~ 0.84
- **New LWC are estimated** considering **the uncertainty in LWC**
  - Using the LWC calibrated to rime ice thickness
  - **0.761 g/m<sup>3</sup> will be used for LWC**

	Case 1.	Case 2.	Case 3.	Case 4.	Case 5.
<b>VTT IWT</b>					
LWC <sub>Theoretical</sub> [g/m <sup>3</sup> ]	0,25	0,44	0,44	0,25	0,44
<b>ICEMET</b>					
MVD [μm]	25,5±0,7	24,3±0,4	25,7±0,5	16,1±0,3	16,6±0,2
LWC [g/m <sup>3</sup> ]	0,27±0,03	0,42±0,03	0,48±0,02	0,22±0,03	0,46±0,05
<b>CDP FMI</b>					
MVD [μm]	18,5±1,7	17,8±1,4	-	13,5±0,4	14,1±1,0
LWC [g/m <sup>3</sup> ]	0,45±0,06	0,81±0,12	-	0,56±0,14	0,84±0,33
<b>CDP DTU</b>					
MVD [μm]	18,5±1,6	18,8±1,7	-	13,8±0,8	-
LWC [g/m <sup>3</sup> ]	0,34±0,05	0,74±0,13	-	0,52±0,10	-

▲ Results of validation measurement [6]



▲ VTT icing wind tunnel validation material [6]



▲ Calibrated LWC to match the ice thickness

# RESULTS & DISCUSSION

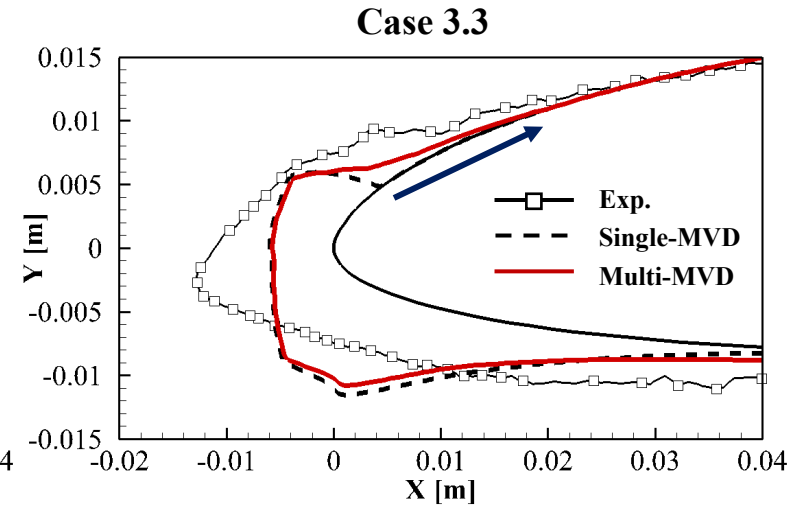
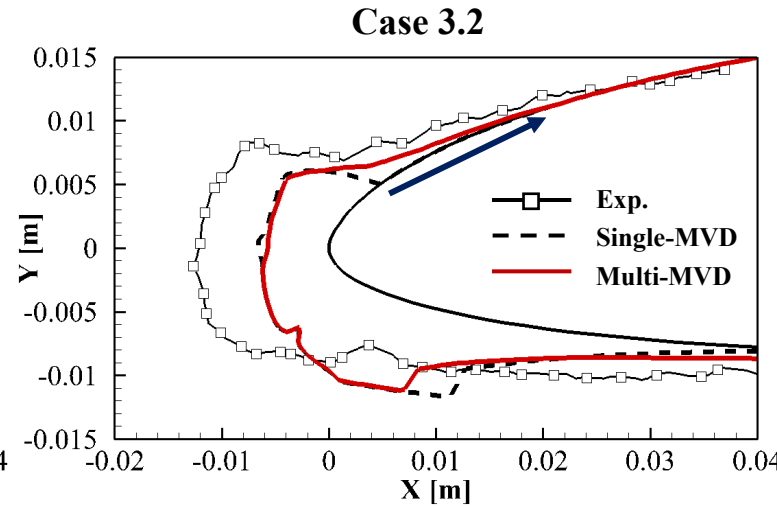
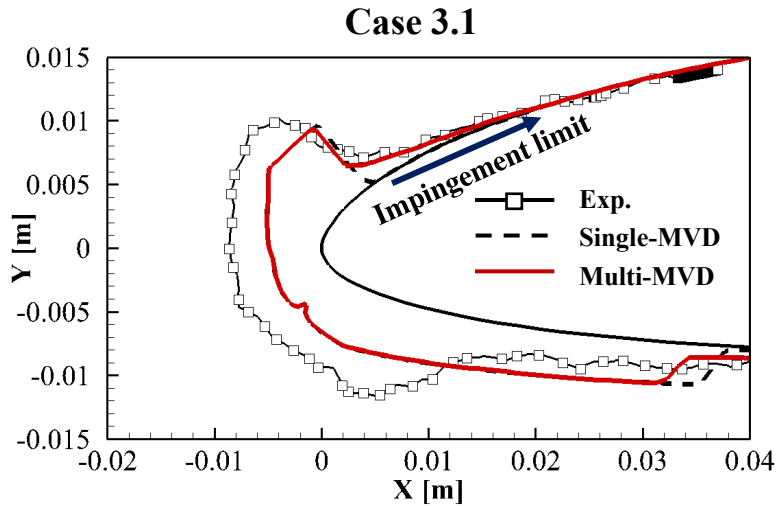
## ■ Case 3 : RG-15 low speed Icing

### • Icing results

#### ✓ Comparison of **MVD approach**

- Single MVD
  - 23  $\mu\text{m}$
- Multi-MVD based on IRT droplet distribution
  - 6.5, 11.2, 15.7, 22.7, 32.9, 59.5, and 96.7  $\mu\text{m}$
- **Multi-MVD** has much **better agreement of impingement limit**
  - Multi-MVD approach will be used

Multi MVD / Single shot / 2D roughness value					
Case No.	Speed (m/s)	$T_{static}$ ( $^{\circ}\text{C}$ )	MVD ( $\mu\text{m}$ )	LWC ( $\text{g}/\text{m}^3$ )	Time (min.)
3.1	25	-2	23	0.761	20
3.2	25	-4	23	0.761	20
3.3	25	-10	23	0.761	20



▲ Ice shape comparison between experiment and simulation

# RESULTS & DISCUSSION

## ■ Case 3 : RG-15 low speed Icing

### • Icing results

✓ Comparison of **Single & Multi-shot approach**

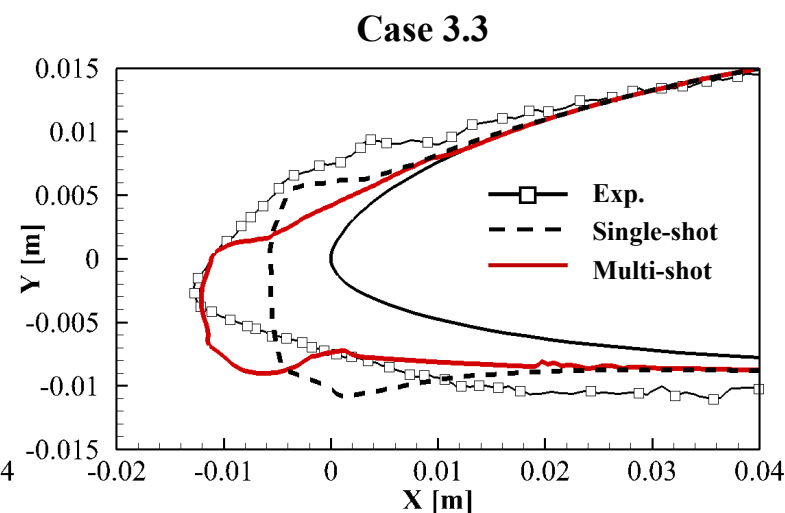
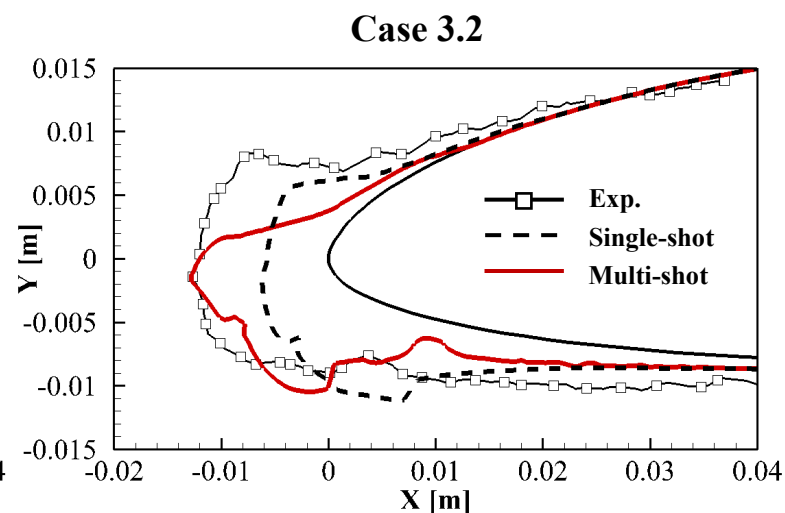
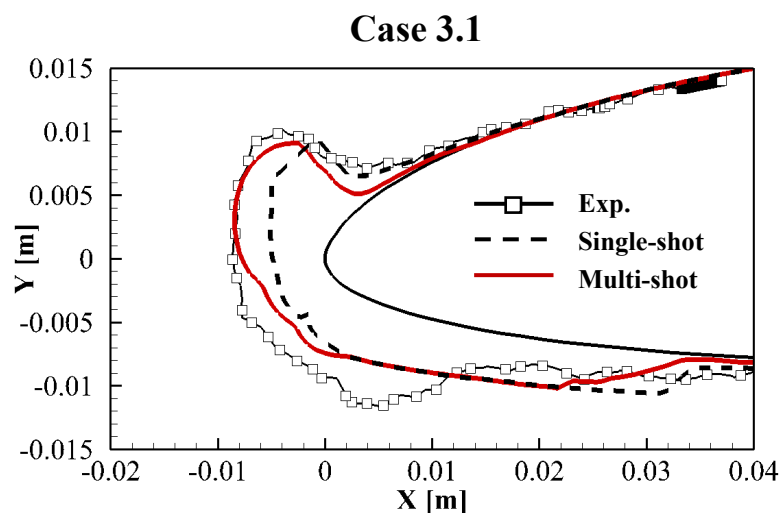
- Single-shot approach

- Multi-shot approach

• **4 step** was applied

➤ **Multi-shot** has much **better agreement of ice thickness**

Multi MVD / Multi shot / 2D roughness value					
Case No.	Speed (m/s)	$T_{static}$ (°C)	MVD ( $\mu\text{m}$ )	LWC ( $\text{g}/\text{m}^3$ )	Time (min.)
3.1	25	-2	23	0.761	20
3.2	25	-4	23	0.761	20
3.3	25	-10	23	0.761	20



▲ Ice shape comparison between experiment and simulation

# CONCLUSIONS

---

# CONCLUSION

## ■ Case 1 & 2 : CRM-65 hybrid (3D)

- Multi-MVD has much better agreement of impingement limit
- Roughness values smaller than calibrated values to 2D cases show better ice horn angle
  - ✓ Especially, roughness value calibrated to 2D multiplied by 0.01 shows best agreement
  - ✓ However, it is necessary to calibrate the roughness value to numerous data for scallop cases

## ■ Case 3 : RG-15 low speed Icing

- Calibrated LWC are used considering the possibility of uncertainty in LWC
  - ✓ LWC value was set to match the rime ice thickness
  - ✓ Simulation results show good agreement with ice thickness in all case
  - ✓ Especially in case 3.1, ice horn angle are accurately predicted

# THANK YOU FOR YOUR ATTENTION

---

## Contact information

Soonho Shon : [hho6023@snu.ac.kr](mailto:hho6023@snu.ac.kr)

Prof. Kwanjung Yee : [kjyee@snu.ac.kr](mailto:kjyee@snu.ac.kr)

Lab. homepage : <http://avdl.snu.ac.kr>





# APPENDIX

## ■ Roughness model

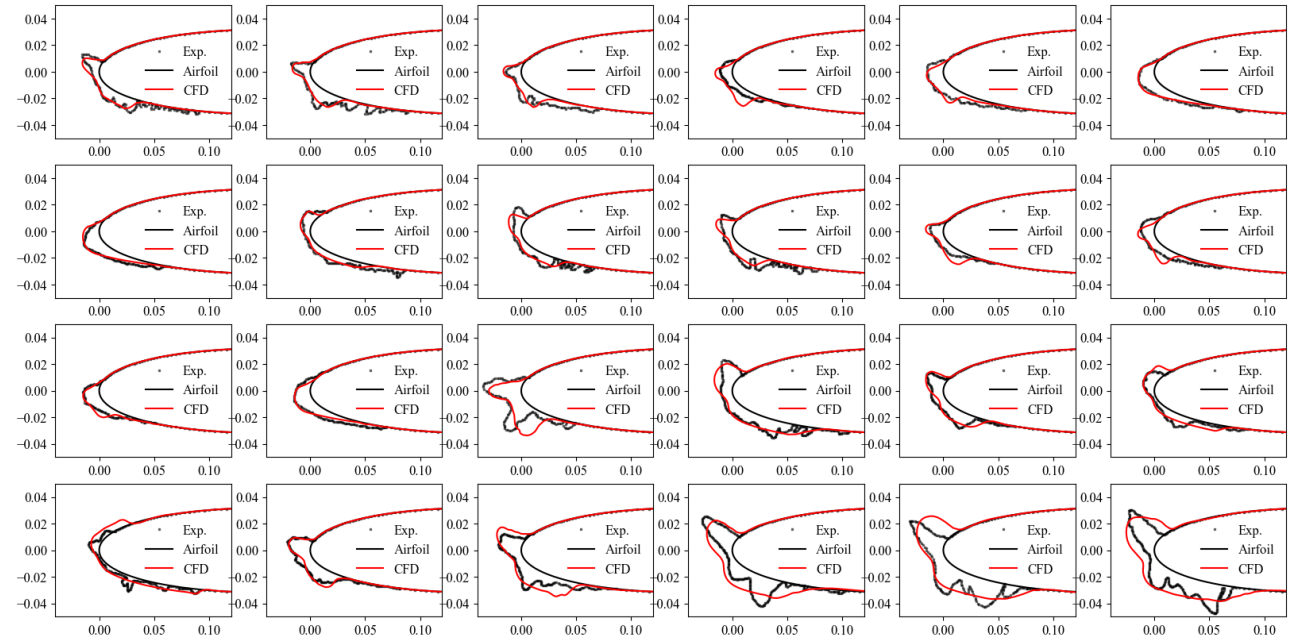
- Fortin's ESGR model calibrated for ICEPAC
  - ✓ Generalizable roughness model based on icing scaling parameters

$$- \left(\frac{\kappa_S}{c}\right)^n \propto \beta \frac{LWC}{\rho_{air} c_{p,air}(T_f - T_{rec})} \frac{L_f}{c} \rightarrow \left(\frac{\kappa_S}{c}\right)^{0.3} = a \ln \left[ \beta \frac{LWC}{\rho_{air} c_{p,air}(T_f - T_{rec})} \frac{L_f}{c} \right] + b$$

- ✓ Wide range of icing conditions were included for calibration (NASA validation cases)

Case	LWC	MVD	T	V	AoA	$\tau$	Case	LWC	MVD	T	V	AoA	$\tau$
1	0.55	20	265.37	102.8	4	420	13	1	20	253.4	67.1	4	360
2	0.55	20	263.71	102.8	4	420	14	1	20	244.51	67.1	4	360
3	0.55	20	262.04	102.8	4	420	15	0.55	20	262.04	102.8	4	840
4	0.55	20	259.82	102.8	4	420	16	1.6	30	265.07	67.1	4	360
5	0.55	20	256.49	102.8	4	420	17	1.3	20	266.19	58.1	4	480
6	0.55	20	250.37	102.8	4	420	18	1.3	20	269.19	58.1	4	480
7	0.55	20	241.49	102.8	4	420	19	1.3	20	270.19	58.1	4	480
8	1	20	268.4	67.1	4	360	20	1.3	20	263.19	58.1	4	480
9	1	20	266.74	67.1	4	360	21	1	30	262.04	102.8	4	360
10	1	20	265.07	67.1	4	360	22	1.3	30	262.04	102.8	4	360
11	1	20	262.85	67.1	4	360	23	1.6	30	262.04	102.8	4	360
12	1	20	259.51	67.1	4	360	24	1.8	30	262.04	102.8	4	360

▲ Validation cases used for roughness calibration



▲ Roughness calibration result ( $a = 0.068, b = 0.4$ )

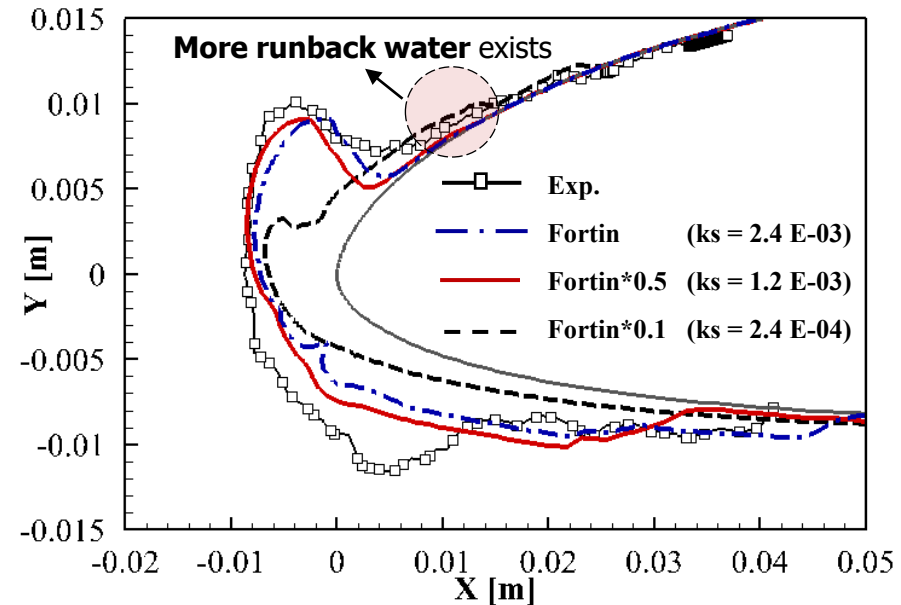
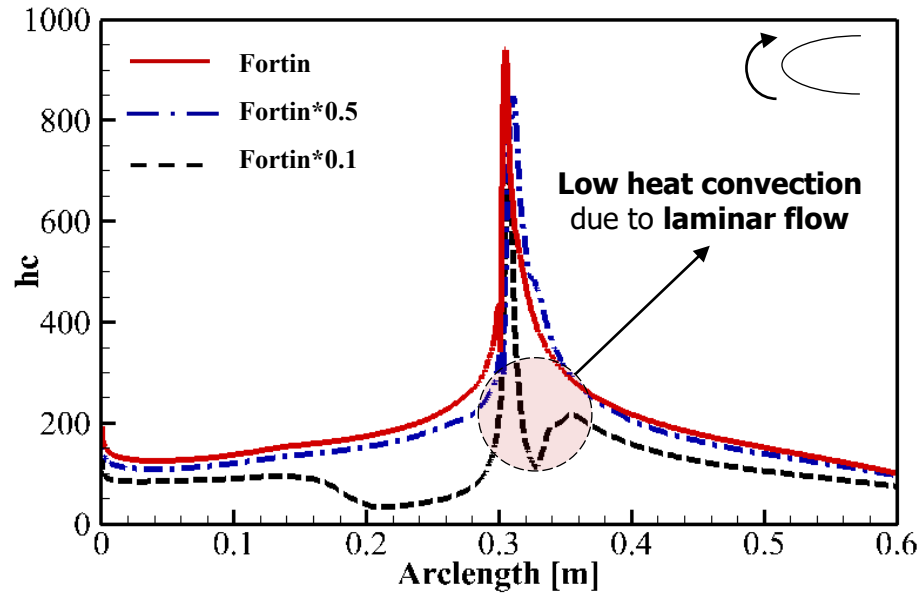
## ■ Case 3 : RG-15 low speed Icing

### • Icing results

✓ Effect of **heat convection** according to **transition**

- Change of the heat convection with different roughness value
  - Calibrated roughness value
  - Calibrated roughness value multiplied by **0.5**
  - Calibrated roughness value multiplied by **0.1** -> **Flow transition** exists

Multi MVD / Multi shot / Varied roughness value					
Case No.	Speed (m/s)	$T_{static}$ (°C)	MVD ( $\mu m$ )	LWC ( $g/m^3$ )	Time (min.)
3.1	25	-2	24	0.761	20
3.2	25	-4	24	0.761	20
3.3	25	-10	24	0.761	20



▲ Comparison of heat convection and ice shape in Case 3.1

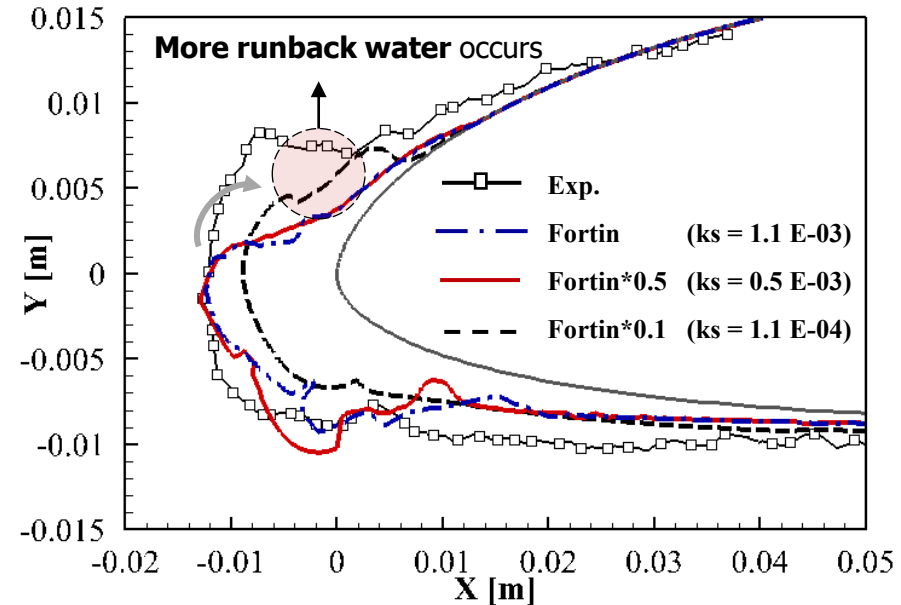
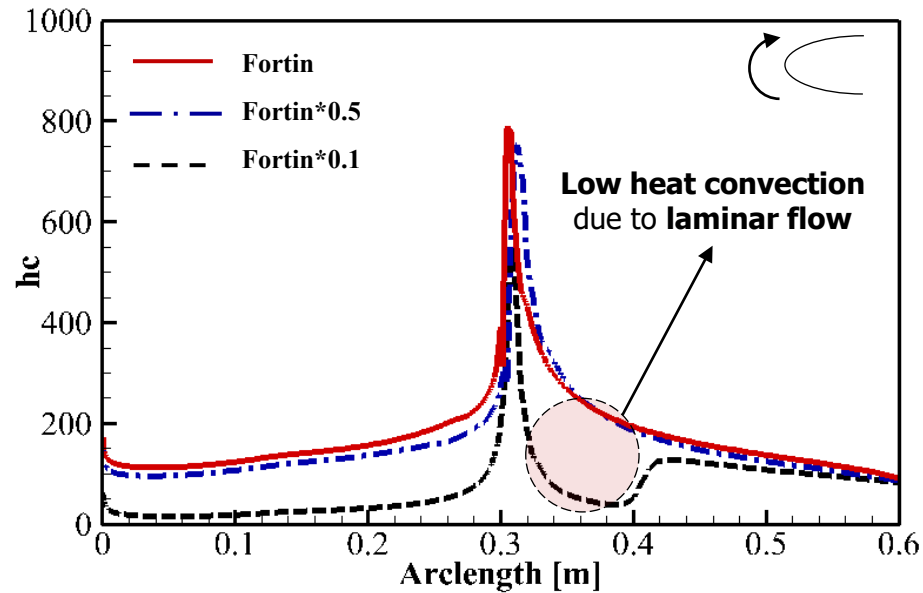
## Case 3 : RG-15 low speed Icing

### Icing results

✓ Effect of **heat convection** according to **transition**

- Change of the heat convection with different roughness value
  - Calibrated roughness value
  - Calibrated roughness value multiplied by **0.5**
  - Calibrated roughness value multiplied by **0.1** -> **Flow transition** exists

Multi MVD / Multi shot / Varied roughness value					
Case No.	Speed (m/s)	$T_{static}$ (°C)	MVD ( $\mu m$ )	LWC ( $g/m^3$ )	Time (min.)
3.1	25	-2	24	0.761	20
3.2	25	-4	24	0.761	20
3.3	25	-10	24	0.761	20



▲ Comparison of heat convection and ice shape in Case 3.1