

Quotients

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Geometry and Lie theory.
Dedicated to Eldar Straume on his 70th birthday.
Trondheim, 03.11.16

Plan of the talk

- Some observations and quasi historical remarks

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 - invariants of irreducible representations of semisimple Lie groups

The General Moduli Problem

"Describe" the orbit space Ω/G of a group G -action on a space Ω .

Main collection:

- Ω - is a smooth manifold, G - is a Lie group, $G \times \Omega \rightarrow \Omega$ proper and free action $\implies \Omega/G$ smooth manifold and $\Omega \rightarrow \Omega/G$ is a principal G -bundle (J.L. Koszul and R. Palais).
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- Ω - is an affine manifold, G -is a semi-simple Lie group, $G \times \Omega \rightarrow \Omega$ -algebraic action $\implies \Omega/G$ affine manifold (D. Hilbert).
Regular orbits are separated by *polynomial invariants*.

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Regular orbits are separated by *polynomial invariants*.

- Ω - is an algebraic manifold, G - is an algebraic Lie group, $G \times \Omega \rightarrow \Omega$ -algebraic action \implies regular orbits are separated by *rational invariants* (M. Rosenlicht).

There is no Hilbert's 14th problem!

The Differential Moduli Problem

"Describe" the orbit space Ω/G , where Ω is a solution space of a differential equation and G is a symmetry pseudogroup.

Jet level:

PDEs system $\mathcal{E} \subset \mathbf{J}^\infty$, G -symmetry Lie pseudogroup.

- $\mathcal{E} = \mathbf{J}^\infty$.

Lie-Tresse Theorem: Microlocally (i.e. in a neighborhood of \mathbf{J}^∞) algebra differential G -invariants is generated by a number of basic differential invariants and G -invariant total derivations. (S. Lie, A. Tresse, A. Kumpera for Lie pseudogroups and L. Ovsyannikov and P. Olver for Lie groups).

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- Lie-Tresse Theorem for PDEs: $\mathcal{E} \subset \mathbf{J}^\infty$ is a formally integrable PDEs system, G -Lie pseudogroup of symmetries. (B.Kruglikov & VL).

Basic Setup

- M is a smooth manifold, $\mathbf{J}_0^k(M, M)$ - the manifold of k -jets of diffeomorphisms of M , $\mathbf{J}^k(M, n)$ - the manifold of k -jets of submanifolds in M , having dimension n .

Affine and algebraic structures:

$$\dots \longrightarrow \mathbf{J}^3(M, n) \xrightarrow{\mathbf{S}^3\mathbf{T}^* \otimes \nu} \mathbf{J}^2(M, n) \xrightarrow{\mathbf{S}^2\mathbf{T}^* \otimes \nu} \mathbf{J}^1(M, n) \xrightarrow{\text{Gr}_n(\mathbf{T}M)} M$$

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- $\mathcal{E} \subset \mathbf{J}^\infty(M, n)$, $\{\mathcal{E}^k \subset \mathbf{J}^k(M, n)\}$, is a PDEs system on submanifolds (of dimension n) of M .
- Given point $a \in M$, by \mathbf{J}_a^k and \mathcal{E}_a^k we denote the fibres of projections $\mathbf{J}^k(M, n) \rightarrow M$ and $\mathcal{E}^k \rightarrow M$ at the point a , G_a^k are stabilizers G^k of the point.

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- The prolonged actions of G on $\mathbf{J}^k(M, n)$, $k = 1, 2, \dots$ are *algebraic*. That is, G_a^k are algebraic groups acting algebraically on algebraic manifolds \mathbf{J}_a^k .
- \mathcal{E} is G -invariant formally integrable PDE system and $\mathcal{E}_a^k \subset \mathbf{J}_a^k$ are irreducible algebraic submanifolds.

- "Common sense": A smooth function I densely defined on equation $\mathcal{E}^l \subset \mathbf{J}^l(M, n)$ and invariant with respect to the prolonged G -action is called a *differential G -invariant* of order $\leq l$.

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- "Common sense": A smooth function I densely defined on equation $\mathcal{E}^I \subset \mathbf{J}^I(M, n)$ and invariant with respect to the prolonged G -action is called a *differential G -invariant* of order $\leq I$.
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- "Good sense": By a *differential G -invariant* of order $\leq I$ we mean a differential G -invariant which is rational along fibres $\pi_{s,0} : \mathcal{E}^s \rightarrow M$, for some $s \leq I$, and polynomial along fibres $\pi_{I,s} : \mathcal{E}^I \rightarrow \mathcal{E}^s$.

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- Similar to the case of differential invariants we'll play with coefficients of the total vector fields in order to get invariant derivations in "good sense".
- In reality, one needs derivations but not only total vector fields!

Cartan-Kuranishi type theorem for singularities

We say that a closed subset $S \subset \mathcal{E}^k$ is *Zariski closed* if all its intersections $S_a = S \cap \mathbf{J}_a^k$ are Zariski closed.

Theorem

There exists a number l and a Zariski closed invariant proper subset $\Sigma_l \subset \mathcal{E}^l$ such that the action is regular in $\mathcal{E}^k \setminus \pi_{\infty, l}^{-1}(\Sigma_l)$ i.e. for any $k \geq l$, the orbits of G on $\mathcal{E}^k \setminus \pi_{k, l}^{-1}(\Sigma_l)$ are closed, have the same dimension and separated by "good" differential invariants.

Our second result gives finiteness for differential invariants.

Theorem

There exists a number l and a Zariski closed invariant proper subset $\Sigma_l \subset \mathcal{E}^l$ such that the algebra of good differential invariants separates the regular orbits and is finitely generated in the following sense.

There exists a finite number of good differential invariants I_1, \dots, I_n and of good invariant derivations $\nabla_1, \dots, \nabla_s$ such that any good differential invariant is a polynomial of $\nabla_J(I_i)$, where $\nabla_J(I_i) = \nabla_{j_1} \circ \dots \circ \nabla_{j_r}$, for some multi-indices J , with coefficients being rational functions of I .

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- The theorem holds if G acts in a transitive way on some manifold \mathcal{E}^k . Then all algebraic properties should be required for bundles $\pi_{r,k} : \mathcal{E}^r \rightarrow \mathcal{E}^k$, where $r > k$.

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- An important issue (not appearing micro-locally) is that some of the derivations ∇_j may not be represented by total vector fields.
- Finiteness theorem valid invariant differential forms, tensors and other natural geometric objects.

Arnold conjecture on Poincarè function

V. Arnold (1994) made a conjecture that Poincarè functions in differential moduli problems are rational.

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- Then:
 - 1 The Hilbert function H_G is a polynomial for large k .
 - 2 The Poincaré function equals

$$P_G(z) = \frac{p(z)}{(1-z)^d},$$

for some polynomial $p(z)$ and integer $d > 0$.

Riemannian structures

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Riemannian structures

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- We say that metric g is *Ricci regular* at a point $a \in M$ if total differentials $\widehat{d}J_1, \widehat{d}J_2, \dots, \widehat{d}J_n$ are linear independent at the point $a_3 = [g]_a^3 \in \mathbf{J}^3(\mathbf{S}^2\mathbf{T}^*)$.

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- Denote by

$$\Sigma_3 = \{\widehat{d}J_1 \wedge \widehat{d}J_2 \wedge \dots \wedge \widehat{d}J_n = 0\} \subset \mathbf{J}^3(\mathbf{S}^2\mathbf{T}^*)$$

be the set of Ricci singular points.

Differential invariant algebra

Basic invariants

At Ricci regular points we represent the metric in the following form

$$g = \sum_{i \leq j} G_{ij} \widehat{d}J_i \cdot \widehat{d}J_j.$$

Then G_{ij} are rational differential invariants of order 3 defined at Ricci regular points $\mathbf{J}^3(\mathbf{S}^2\mathbf{T}^*) \setminus \Sigma_3$.

Differential invariant algebra

Basic derivations

The Tresse derivations

$$\nabla_1 = \frac{D}{DJ_1}, \dots, \nabla_n = \frac{D}{DJ_n}$$

are rational, defined and linear independent at Ricci regular points.

The basic frame formed by gradients of basic invariants:

$$E_1 = \text{grad}_g J_1, \dots, E_n = \text{grad}_g J_n.$$

By differential invariant of order k we mean an invariant which is rational along fibres $\mathbf{J}^k(\mathbf{S}^2\mathbf{T}^*) \rightarrow M$ and polynomial along fibres $\mathbf{J}^k(\mathbf{S}^2\mathbf{T}^*) \rightarrow \mathbf{J}^3(\mathbf{S}^2\mathbf{T}^*)$.

Theorem

Algebra metric differential invariants generated by basic invariants G_{ij} and Tresse derivatives $\nabla_1, \dots, \nabla_n$.

Metric differential invariants

Factor equation

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$$J = (J_1(g), \dots, J_n(g)),$$

where $J_i(g)$ are the values of J_i at metric g , Σ_g - Ricci singular points, $\mathbf{D}_g = \text{Im}(J)$.

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$$W_g : \Lambda^2 \mathbf{T}^* \rightarrow \Lambda^2 \mathbf{T}^*$$

the Weyl tensor. Then the Hodge operator $*$: $\Lambda^2 \mathbf{T}^* \rightarrow \Lambda^2 \mathbf{T}^*$ defines a complex structure in the bundle $\Lambda^2 \mathbf{T}^*$ and W_g is \mathbb{C} -linear operator with $\text{Tr}_{\mathbb{C}} W_g = 0$.

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Theorem

Algebra differential invariants for Einstein metrics is generated by basic invariants G_{ij} and Tresse derivatives $\nabla_1, \dots, \nabla_4$.

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$$J_1 = H, J_2 = \nabla(H), J_3 = \nabla^2(H)$$

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Theorem

Two regular binary forms are $\mathbf{GL}(2, \mathbb{C})$ -equivalent iff their invariants coincide (up to multiplier).

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Thank you for your attention