

TFY4305 solutions exercise set 5 2014

Problem 3.5.4

a) Looking at Fig. 1 in the textbook, we see that the restoring force is given

$$F = (\sqrt{h^2 + x^2} - L_0)k. \quad (1)$$

The force is in the direction of the spring. We need the component of the force along the wire, which is given by

$$\begin{aligned} F_{\text{wire}} &= F \sin \theta \\ &= F \frac{x}{\sqrt{h^2 + x^2}}, \end{aligned} \quad (2)$$

Newton's second law of motion then becomes

$$m\ddot{x} + b\dot{x} + kx \left(1 - \frac{L_0}{\sqrt{h^2 + x^2}}\right) = 0. \quad (3)$$

b) Equilibrium solutions are given by $\ddot{x} = \dot{x} = 0$. This yields

$$kx \left(1 - \frac{L_0}{\sqrt{h^2 + x^2}}\right) = 0. \quad (4)$$

Thus $x = 0$ and $1 - \frac{L_0}{\sqrt{h^2 + x^2}} = 0$. This gives $\underline{x = 0}$ and $\underline{x = \pm\sqrt{L_0^2 - h^2}}$. The nonzero solutions exist only if $L_0 \geq h$.

c) If $m = 0$, the equation of motion reads

$$\dot{x} = \frac{kx}{b} \left(\frac{L_0}{\sqrt{h^2 + x^2}} - 1\right). \quad (5)$$

The function that determines the stability of the fixed points is

$$f(x) = \frac{kx}{b} \left(\frac{L_0}{\sqrt{h^2 + x^2}} - 1\right). \quad (6)$$

The derivative is given by

$$f'(x) = \frac{k}{b} \left(\frac{L_0}{\sqrt{h^2 + x^2}} - 1 - \frac{L_0 x^2}{(k^2 + x^2)^{\frac{3}{2}}} \right). \quad (7)$$

This yields

$$f'(0) = \frac{k}{b} \left(\frac{L_0}{h} - 1 \right) \quad (8)$$

The origin is stable for $L_0 < h$ and unstable for $L_0 > h$. Moreover

$$f'(\pm\sqrt{L_0^2 - h^2}) = \frac{k}{b} \left(1 - \frac{L_0^2}{h^2} \right). \quad (9)$$

Thus the fixed points $x = \pm\sqrt{L_0^2 - h^2}$ are stable since $L_0 \geq h$. The stability of the fixed points depends on the ratio $y \equiv L_0/h$. We therefore plot the bifurcation diagram as a function of this dimensionless variable.

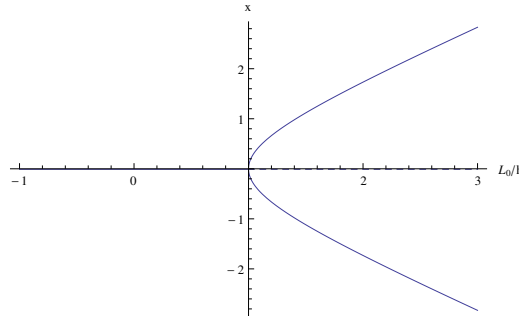


Figure 1: Bifurcation diagram for the bead on a wire. The origin changes stability in $x = 0$.

d) We can rewrite the equation of motion as

$$\frac{m}{k} \frac{d^2 x}{dt^2} + \frac{b}{k} \frac{dx}{dt} + x \left(1 - \frac{L_0}{\sqrt{h^2 + x^2}} \right) = 0. \quad (10)$$

Defining a new dimensionless time variable τ via

$$t = \frac{b}{k} \tau. \quad (11)$$

In terms of the new time variable, Newton's equation reads

$$\frac{m}{k} \frac{k^2}{b^2} \frac{d^2 x}{d\tau^2} + \frac{dx}{d\tau} + x \left(1 - \frac{L_0}{\sqrt{h^2 + x^2}} \right) = 0. \quad (12)$$

One can therefore ignore the second-order term if

$$\frac{mk}{b^2} \ll 1. \quad (13)$$

Problem 3.6.5

The forces acting on the bead are gravity and the force from the spring (see Fig. 3.6.7). The component of gravity along the wire is $F = mg \sin \theta$. The force from the spring is

$$F_{\text{spring}} = k \left(\sqrt{x^2 + a^2} - L_0 \right). \quad (14)$$

The component of this force along the wire is

$$F_{\text{wire}} = -\frac{x}{\sqrt{x^2 + a^2}} F_{\text{spring}}. \quad (15)$$

The sum of F and F_{wire} is zero when the system is in equilibrium. This yields

$$mg \sin \theta - kx \left(1 - \frac{L_0}{\sqrt{x^2 + a^2}} \right) = 0. \quad (16)$$

b) Dividing Eq. (16) by kx , we can write

$$\frac{mg}{kx} \sin \theta = \left(1 - \frac{L_0}{a} \frac{1}{\sqrt{1 + \left(\frac{x}{a}\right)^2}} \right). \quad (17)$$

Rearranging terms, we find

$$1 - \frac{mg}{ka} \frac{a}{x} \sin \theta = \frac{L_0}{a} \frac{1}{\sqrt{1 + \left(\frac{x}{a}\right)^2}}. \quad (18)$$

This is on the form

$$1 - \frac{h}{u} = \frac{R}{\sqrt{1 + u^2}}, \quad (19)$$

if we identify $u = x/a$, $R = L_0/a$, and $h = \frac{mg}{ka} \sin \theta$.

c) Note that the variable u can be positive and negative. Without loss of generality we can restrict h to positive values (negative values correspond to tilting the wire the other way) The function $g(u) = 1 - h/u$ approaches zero as $u \rightarrow \pm\infty$. The maximum of the function $h(u) = R/\sqrt{1 + u^2}$ is R . For $R < 1$, it is then clear that the functions intersect at a single point and hence there is one fixed point. This is shown in Fig. 2

For $R > 1$, the function $g(u)$ still intersects the function $h(u)$ for positive values of u . However, there may be one or two intersections for negative values of u depending on h . In fact, as Figs. 3 and 4 suggest, a saddle-node bifurcation is taking place at a critical value of h . Since the derivatives of the functions $g(u)$ and $h(u)$ are equal at the bifurcation, h and u satisfy the two equations

$$1 - \frac{h}{u} = \frac{R}{\sqrt{1 + u^2}}, \quad (20)$$

$$\frac{h}{u^2} = -\frac{Ru}{(1 + u^2)^{\frac{3}{2}}}. \quad (21)$$

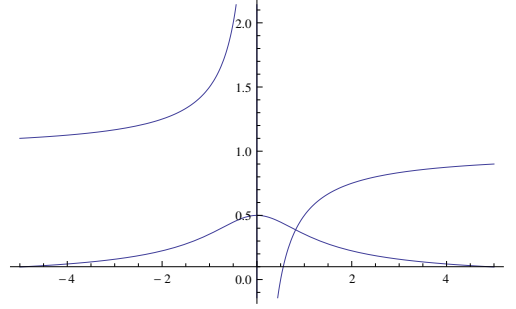


Figure 2: Graphical analysis. $R = \frac{1}{2}$ and $h = \frac{1}{2}$.

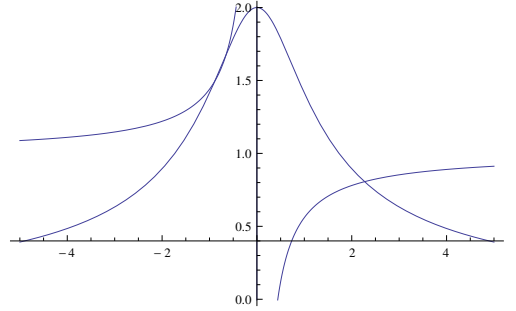


Figure 3: Graphical analysis. $R = 2$ and $h = 0.44$.

d) The right-hand-side of Eq. (19) can be expanded in powers of u . This yields

$$1 - \frac{h}{u} \approx (r+1)\left(1 - \frac{1}{2}u^2\right), \quad (22)$$

where $r = R - 1$. Ignoring the term $\sim ru^2$ which is much smaller than the term $\sim u^2$, we obtain

$$-\frac{h}{u} \approx r - \frac{1}{2}u^2, \quad (23)$$

or

$$\underline{\underline{\frac{1}{2}u^3 - ru - h = 0}}. \quad (24)$$

e) We first define the functions $f(u) = \frac{1}{2}u^3 - ru$ and $g(u) = h(u)$. The bifurcation takes place when $f(u) = g(u)$ and $f'(u) = g'(u)$. The latter equation gives

$$\frac{3}{2}u^2 - r = 0. \quad (25)$$

This yields $R(u) = 1 + \frac{3}{2}u^2$. The equation $g(u) = h(u)$ gives $h(u) = \frac{1}{2}u^3 - ru = -u^3$

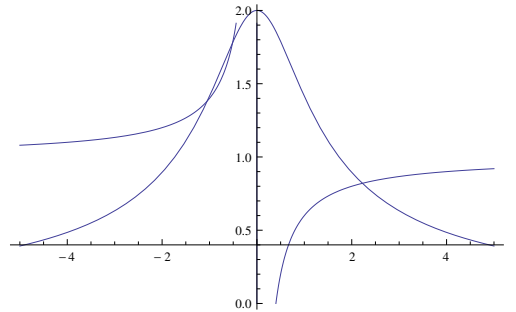


Figure 4: Graphical analysis. $R = 2$ and $h = 0.4$.

f) The exact equations for the bifurcation are given by Eqs. (20) and (21). Solving the latter with respect to $\frac{h}{u}$ and inserting it into the former, one finds

$$1 + \frac{Ru^2}{(1+u^2)^{\frac{3}{2}}} = \frac{R}{\sqrt{1+u^2}}. \quad (26)$$

Solving this equation with respect to R gives

$$\underline{\underline{R(u) = (1+u^2)^{\frac{3}{2}}}}. \quad (27)$$

Using Eq. (20), we find

$$\underline{\underline{h(u) = -\frac{Ru^3}{(1+u^2)^{\frac{3}{2}}} = -u^3}}. \quad (28)$$

Note that the exact Eqs. (27) and (28) reduce to the approximate solutions upon expanding $R(u)$ to first nontrivial order in u for small u .

g) and h) were not a part of the exercise.