Suggested solution Mathematical modelling Exercise 3, autumn 2005

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Exercise 1

We use Buckingham's Pi theorem directly:

$$[D] = [m], \qquad [\rho] = \left[\frac{\mathrm{kg}}{\mathrm{m}^3}\right],$$
$$[h] = [m], \qquad [d] = [m],$$
$$[E] = \left[\frac{\mathrm{kg}}{\mathrm{m}\,\mathrm{s}^2}\right], \quad [\delta] = [m],$$
$$[g] = \left[\frac{\mathrm{m}}{\mathrm{s}^2}\right].$$

From these 7 quantities involving 3 dimensions, we excpect to find 7-3 = 4 dimensionless quantities, for example¹

$$\pi_1 = \frac{\delta}{D}, \quad \pi_2 = \frac{h}{D}$$
$$\pi_3 = \frac{d}{D}, \quad \pi_4 = \frac{E}{Dg\rho}$$

According to Buckingham's theorem, the wanted relation can be written

$$\frac{\delta}{D} = \phi\left(\frac{h}{D}, \frac{d}{D}, \frac{E}{Dg\rho}\right).$$

Obviously, the bottom of the tank sags because of the pressure of the water, which is given as $p = \rho g h$ on the bottom of the tank. We can get rid all occurences of *rho*, *g* and *h* except for the combination $\rho g h$ by replacing π_2 and π_4 by π_4/π_2 , leading to

$$\frac{\delta}{D} = \phi\left(\frac{d}{D}, \frac{E}{hg\rho}\right).$$

Of course, we could have arrived at this directly if we had the good foresight to replace *D* by *h* in the definition of π_4 . Even better, we could have started out with the five relevant variables *D*, *p*, *d*, *E*, δ and saved a bit of work.

¹The first three are sort of obvious, and π_4 can also be found by inspection: To include *E* in a dimensionless combination, we need to divide by ρ in order to get rid of all kilograms. Then E/ρ needs to be divided by *g* to get rid of the seconds, and we're left with a length, so we divide by one of the length parameters.

Exercise 2

We start out with the quantities and their dimensions:

$$[V] = [m^3], \qquad [\rho] = \left[\frac{kg}{m^3}\right], \quad [t] = [s],$$
$$[P] = \left[\frac{kg}{ms^2}\right], \quad [\mu] = \left[\frac{kg}{ms}\right].$$

From these 5 quantities expressed in 3 dimensions, we expect to extract 5-3 = 2 independent dimensionless quantities. There are many ways to do this, but for the best correspondence with the original *P* vs *t* graphs we should look for two combinations where one contains *P* but not *t*, and the other contains *t* but not *P*. This produces

$$\pi_1 = \frac{\mu t}{V^{2/3}\rho}, \quad \pi_2 = \frac{V^{2/3}\rho P}{\mu^2}$$

Buckingham's theorem states that, if *t* is a function of the other parameters, this can be written as $\pi_1 = \phi(\pi_2)$ – so the axes in the unified graph should be π_2 (horizontal) and π_1 (vertical).

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For any of these materials, use the thermal diffusion coefficient $\kappa = \frac{k}{\rho c}$. From our work with the heat equation we know that $[\kappa] = [m^2/s]$, and that heat diffuses a distance $\delta \sim \sqrt{\kappa t}$ over a time *t*.

For simplicity, assume a homogeneous fish consisting of all water, fat or protein. Pick t = 30 s according to the design criteria for the instrument.

The different substances produces these δ values:

$$\delta_{\text{water}} \approx 2.0 \,\text{mm}$$

 $\delta_{\text{fat}} \approx 1.2 \,\text{mm}$
 $\delta_{\text{protein}} \approx 1.9 \,\text{mm}.$

Thus it appears that the heat does not penetrate deeply enough to provide any information beyond the first two millimeters or so.