

TKP4140 Process Control
Department of Chemical Engineering NTNU
Autumn 2022 - Exercise 13

Due date: Friday 25 November at 23:59

Problem 1: Decoupling

Consider a 2×2 process

$$y_1 = g_{11}u_1 + g_{12}u_2 \quad (1)$$

$$y_2 = g_{21}u_1 + g_{22}u_2 \quad (2)$$

controlled with two single loop controllers

$$u'_1 = c_1(y_{1s} - y_1) \quad (3)$$

$$u'_2 = c_2(y_{2s} - y_2) \quad (4)$$

Consider the three cases:

1. Decentralized control

$$u_1 = u'_1 \quad (5)$$

$$u_2 = u'_2 \quad (6)$$

2. Standard decoupling

$$u_1 = u'_1 + D_{12}u'_2 \quad (7)$$

$$u_2 = u'_2 + D_{21}u'_1 \quad (8)$$

3. Inverse decoupling

$$u_1 = u'_1 + D_{12}u_2 \quad (9)$$

$$u_2 = u'_2 + D_{21}u_1 \quad (10)$$

For each case, derive the transfer function from the controller outputs (u'_1, u'_2) to the process outputs (y_1, y_2) .

Assume that ideal decoupling is possible, that is:

$D_{12} = -\frac{g_{12}}{g_{11}}$ and $D_{21} = -\frac{g_{21}}{g_{22}}$ are realizable.

$$1. \quad \underline{y_1 = g_{11} u_1' + g_{12} u_2', \quad y_2 = g_{21} u_1' + g_{22} u_2'}$$

$$2. \quad y_1 = g_{11} \left(u_1' - \frac{g_{12}}{g_{11}} u_2' \right) + g_{12} \left(u_2' - \frac{g_{21}}{g_{22}} u_1' \right)$$

$$y_1 = \left(g_{11} - \frac{g_{12} g_{21}}{g_{22}} \right) u_1' + 0 \cdot u_2'$$

$$y_2 = g_{21} \left(u_1' - \frac{g_{12}}{g_{11}} u_2' \right) + g_{22} \left(u_2' - \frac{g_{21}}{g_{22}} u_1' \right)$$

$$y_2 = \left(g_{22} - \frac{g_{21} g_{12}}{g_{11}} \right) u_2' + 0 \cdot u_1'$$

$$\Rightarrow \underline{y_1 = \left(g_{11} - \frac{g_{12} g_{21}}{g_{22}} \right) u_1', \quad y_2 = \left(g_{22} - \frac{g_{12} g_{21}}{g_{11}} \right) u_2'}$$

$$3. \quad y_1 = g_{11} \left(u_1' - \frac{g_{12}}{g_{11}} u_2 \right) + g_{12} u_2$$

$$= g_{11} u_1'$$

$$y_2 = g_{21} u_1 + g_{22} \left(u_2' - \frac{g_{21}}{g_{22}} u_1 \right)$$

$$= g_{22} u_2'$$

$$\Rightarrow \underline{y_1 = g_{11} u_1', \quad y_2 = g_{22} u_2'}$$

Problem 2: Water mixer - RGA

Consider the mixing process from Exercise 12 with

$$G = \begin{bmatrix} k_1 & k_2 \\ 1 & 1 \end{bmatrix}$$

Compute the RGA at steady state. What pairing does this suggest? Does it agree with your suggestion from Exercise 12?

$$\lambda_{11}^* = \frac{k_1^*}{k_1^* - \frac{k_2^* - 1}{1}} = \frac{1}{1 - \frac{k_2^*}{k_1^*}} = \frac{2}{3}$$

$$k_1^* = \frac{60 - 40}{1} = 20 \quad k_2^* = \frac{30 - 40}{1} = -10$$

Using that the sum of each column and row = 1 for RGA:

$$\text{RGA} = \begin{bmatrix} 2/3 & 1/3 \\ 1/3 & 2/3 \end{bmatrix}, \text{ selecting the pairings closest to 1. } \Rightarrow \begin{matrix} q_h \leftrightarrow T \\ q_c \leftrightarrow h \end{matrix}$$