

# STK4080/9080 SURVIVAL AND EVENT HISTORY ANALYSIS

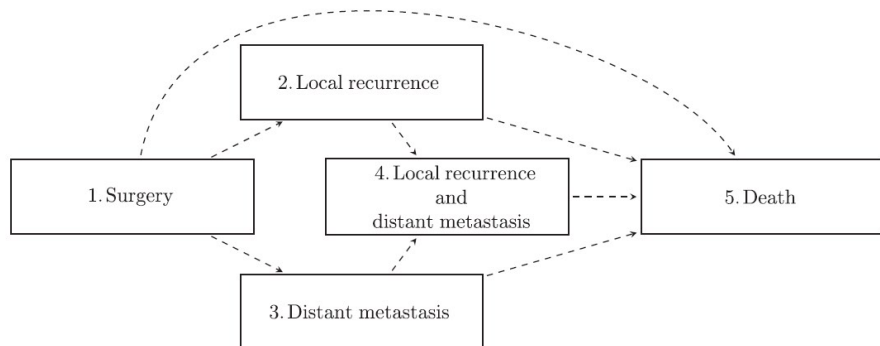
## Slides 9: Multistate models

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## Example: A multistate model for breast cancer



*From:*

Putter, H., Fiocco, M., & Geskus, R. B. (2007). **Tutorial in biostatistics: competing risks and multi-state models.** *Statistics in Medicine*, 26(11), 2389-2430.

# Multistate models

We will consider stochastic processes  $X(t)$  which move within finite state spaces  $\mathcal{S} = \{0, 1, \dots, k\}$ ; e.g.,

We will in particular consider

- ▶ The competing risks model
- ▶ The illness-death (e.g. healthy-illness-death)) model
- ▶ The general case (Aalen-Johansen estimator)

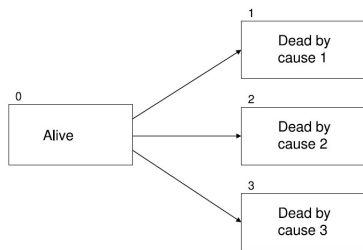


Fig. 3.5 A model for competing risks with  $k = 3$ .

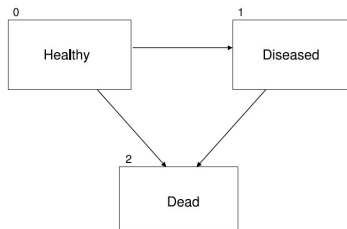


Fig. 3.19 An illness-death model without recovery.

# Competing risks

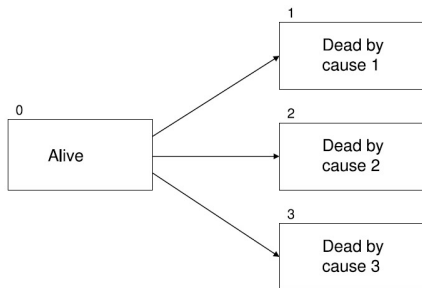


Fig. 3.5 A model for competing risks with  $k = 3$ .

Suppose that for each individual we observe

- ▶ the time to the event of interest (“failure”),  $T$
- ▶ the cause of failure,  $H \in \{1, 2, \dots, k\}$

**The pair  $(T, H)$  is the observation in a case of competing risks.**

# Examples

- ▶ Classical competing risks: Individuals subjected to multiple causes of death, for example
  - ▶ David Bernoulli (1760): How to disentangle the risk of dying from smallpox from other causes.
- ▶ Demography and actuarial sciences
  - ▶ “Multiple-decrement analysis”
- ▶ Cancer research:
  - ▶ Age at onset of cancer and cancer type
  - ▶ Disease relapse vs death in remission
- ▶ Reliability: Breakdown of a mechanical component, with several possible root causes for failure:
  - ▶ vibration
  - ▶ corrosion
  - ▶ etc.

# Latent failure time approach to competing risks

Suppose the  $k$  causes are represented by potential failure times  $T_1, \dots, T_k$

One observes only:

- ▶ The smallest time,  $T = \min_h T_h$
- ▶ Its index  $H = \arg \min_h T_h$  (assumed *unique*)

## Important issues:

- ▶ The marginal distributions of the  $T_j$  are often of primary interest, but are *non-identifiable* in general by observation of  $(T, H)$  only (even if we have an infinite number of observations of  $(T, H)$ )
- ▶ Additional, but non-testable, assumptions may lead to identifiability (for example, independence of the  $T_j$ ).
- ▶ **In biostatistics, one usually avoids the latent failure time approach and restricts attention to the pair  $(T, H)$ .**
- ▶ Independent censoring at time  $C$  can easily be included, leading to the observation of the time  $\tilde{T} = \min(T, C)$  together with  $H$ , where  $H = 0$  means censoring.

## Model specification: **The cumulative incidence function**

- ▶ The joint distribution of the observed pair  $(T, H)$  is given by the **cumulative incidence function**

$$F_h(t) = P(T \leq t, H = h) \quad \text{for } t > 0, h = 1, \dots, k$$

- ▶ The marginal distributions of  $T$  and  $H$  are hence given by

$$F(t) = P(T \leq t) = \sum_{h=1}^k F_h(t) \quad \text{for } t > 0$$
$$\pi_h = P(H = h) = F_h(\infty) \quad \text{for } h = 1, \dots, k$$

## Specification by **cause-specific hazard rates**

- ▶ The distribution of  $(T, H)$  can alternatively be specified by the **cause-specific hazard functions**:

$$\alpha_h(t) = \lim_{\Delta t \rightarrow 0} \frac{P(t < T \leq t + \Delta t, H = h | T > t)}{\Delta t} = \frac{f_h(t)}{S(t)}$$

where  $f_h(t) = F'_h(t)$  is the derivative of the cumulative incidence function and  $S(t) = 1 - F(t)$  is the survival function of  $T$ .

- ▶ It follows that  $f_h(t) = S(t)\alpha_h(t)$  and hence we get, by integration, the sometimes useful formula for the cumulative incidence function,

$$F_h(t) = \int_0^t S(s)\alpha_h(s)ds$$



## General notation of Chapter 3.4 in ABG

We consider stochastic processes  $X(t)$  with state space  $\mathcal{S} = \{0, 1, \dots, k\}$ , assumed to satisfy the Markov assumption:

$$P(X(t) = h | X(s) = g) = P(X(t) = h | X(s) = g, \mathcal{F}_s), \quad s < t, \quad g, h \in \mathcal{S}$$

We can then define *transition probabilities*

$$P_{gh}(s, t) = P(X(t) = h | X(s) = g), \quad s < t, \quad g, h \in \mathcal{S}$$

and *transition intensities*

$$\alpha_{gh}(t) = \lim_{\Delta t \downarrow 0} \frac{1}{\Delta t} P(X(t + \Delta t) = h | X(t-) = g) \quad \text{for } g \neq h$$

## Competing risks (3.4.1 in ABG)

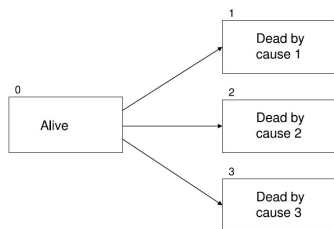


Fig. 3.5 A model for competing risks with  $k = 3$ .

Let  $X(t)$  be the state at time  $t$ . The process then starts at  $X(0) = 0$  and jumps to one (and only one) of the states (“causes”)  $\{1, 2, \dots, k\}$ .

Then if we let  $T$  be the time when the process jumps from state 0, and let  $H$  be the new state entered (i.e. the absorbing state), then we have

$$P_{00}(0, t) = P(T > t) = S(t) \quad (\text{the survival function})$$

$$P_{0h}(0, t) = P(T \leq t, H = h) = F_h(t) \quad (\text{the cumulative incidence function})$$

## Competing risks (3.4.1 in ABG)

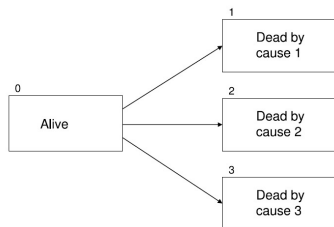


Fig. 3.5 A model for competing risks with  $k = 3$ .

The *cause-specific hazard*  $\alpha_h(t)$  of cause  $h$ , as defined earlier, then is the transition intensity

$$\alpha_{0h}(t) = \lim_{\Delta t \downarrow 0} \frac{1}{\Delta t} P(X(t + \Delta t) = h | X(t-) = 0) \quad \text{for } h = 1, 2, \dots, k$$

which in the counting process framework can be written

$$\alpha_{0h}(t)dt = P(\text{die from cause } h \text{ in } [t, t + dt) | \text{alive at } t-)$$

## Estimation of the cumulative cause-specific hazard

Assume that we have a sample of  $n$  individuals, where each individual is followed from an entry time to death or censoring.

- ▶ Let  $T_1 < T_2 < \dots$  be the times when deaths from any cause are observed,
- ▶ let  $N_{0h}(t)$  be the process counting the number of individuals who are observed to die from cause  $h$  (i.e., make a transition from state 0 to state  $h$ ) in the interval  $[0, t]$ ,
- ▶ let  $N_{0\bullet}(t) = \sum_{h=1}^k N_{0h}(t)$  for the total number of deaths in  $[0, t]$ , and let  $Y_0(t)$  denote the number of individuals at risk (i.e., in state 0) just prior to time  $t$ .

Then the *cumulative cause-specific hazard function* for cause  $h$ ,

$A_{0h}(t) = \int_0^t \alpha_{0h}(s) ds$ , is estimated by the Nelson-Aalen estimator

$$\hat{A}_{0h}(t) = \int_0^t \frac{dN_{0h}(s)}{Y_0(s)} = \sum_{T_j \leq t} \frac{\Delta N_{0h}(T_j)}{Y_0(T_j)}$$

*Notation used here:*  $\Delta N_{0h}(T_j) = \# \text{transitions } 0 \rightarrow h \text{ at } T_j$  (usually 0 or 1)

## Estimation of the cumulative incidence function

The relations:

$$\text{(Survival function)} \quad S(t) = P_{00}(0, t) = \exp \left( - \int_0^t \sum_{h=1}^k \alpha_{0h}(u) du \right)$$

$$\text{(Cumulative incidence)} \quad F_h(t) = P_{0h}(0, t) = \int_0^t P_{00}(0, u-) \alpha_{0h}(u) du$$

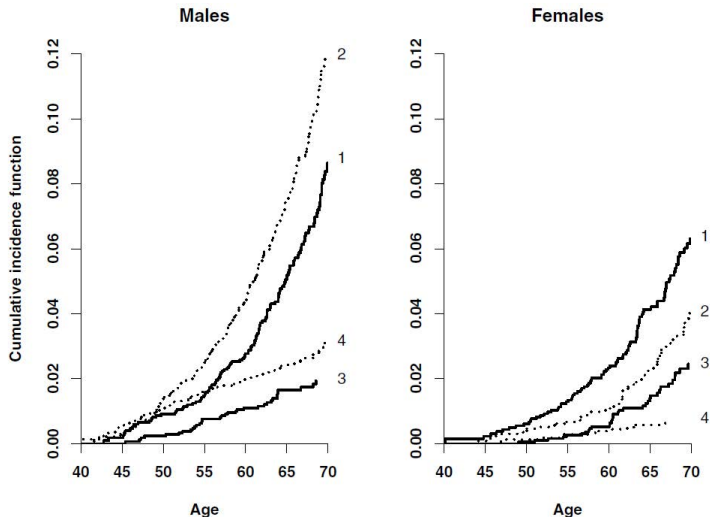
suggest the estimators

$$\hat{P}_{00}(0, t) = \prod_{T_j \leq t} \left( 1 - \frac{\Delta N_{0\bullet}(T_j)}{Y_0(T_j)} \right), \quad \text{where } N_{0\bullet} = \sum_{h=1}^k N_{0h}(t)$$

$$\hat{P}_{0h}(0, t) = \sum_{T_j \leq t} \hat{P}_{00}(0, T_{j-1}) \frac{\Delta N_{0h}(T_j)}{Y_0(T_j)}$$

- ▶  $\hat{P}_{00}(0, t)$  is exactly the KM-estimator for  $S(t)$
- ▶  $\alpha_{0h}(u)$  is estimated by the increment of the NA-estimator for  $A_{0h}(t)$ .

# Estimated cumulative incidence function



**Fig. 3.17** Empirical cumulative incidence functions for four causes of death among middle-aged Norwegian males (left) and females (right). 1) Cancer; 2) cardiovascular disease including sudden death; 3) other medical causes; 4) alcohol abuse, chronic liver disease, and accidents and violence.

## Simulated competing risks data

There are  $n = 1000$  individuals, with latent failure times:

- ▶  $T_1 \sim \text{Weibull}(k = 2, b = 1)$ ,  $P(T_1 > t) = \exp\{-t^2\}$
- ▶  $T_2 \sim \text{Weibull}(k = 0.5, b = 1)$ ,  $P(T_2 > t) = \exp\{-t^{0.5}\}$
- ▶  $C \sim U[0, 2]$ , (censoring times)

The observations are hence  $(\tilde{T}, H)$  where

$$\tilde{T} = \min(T_1, T_2, C), \quad H = 1, 2, 0 \text{ according to whether } \tilde{T} = T_1, T_2, C$$

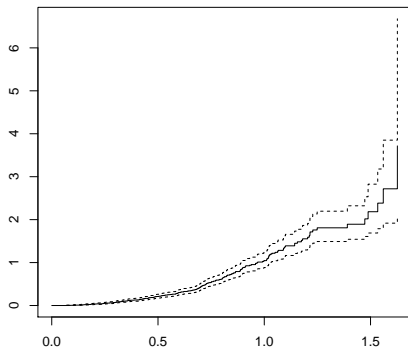
#R-CODE:

```
n=1000
time1=rweibull(n,2)
time2=rweibull(n,0.5)
censtime=runif(n)*2
obstime=pmin(time1,time2,censtime)
h = 1*(obstime==time1)+2*(obstime==time2)
```

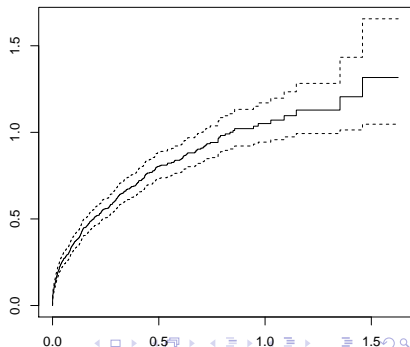
# Estimation of cumulative cause-specific hazard

```
library(survival)
ch1 = survfit(Surv(obstime,h==1)~1,type="fh2")
ch2 = survfit(Surv(obstime,h==2)~1,type="fh2")
par(mfrow=c(1,2))
plot(ch1,fun="cumhaz",mark.time=F,main="Cum.haz.1")
plot(ch2,fun="cumhaz",mark.time=F,main="Cum.haz.2")
```

Cum.haz. 1



Cum.haz. 2



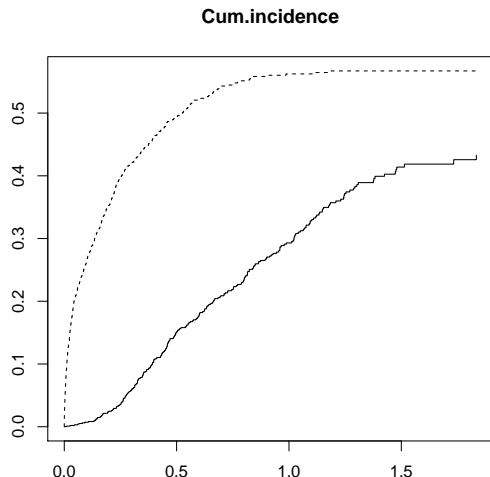


## Estimation of cumulative incidence functions

#Estimation in the 'survival' package

```
ci.surv = survfit(Surv(obstime,h,type="mstate")~1)
```

```
plot(ci.surv,lty=1:2,main="Cum.incidence")
```



# Estimation of cumulative incidence functions

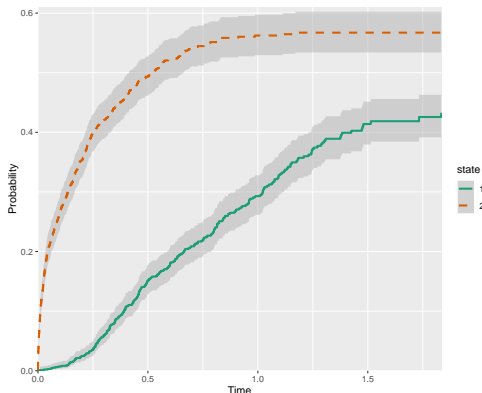
```
#Estimation in the 'mstate' package
```

```
library(mstate)
```

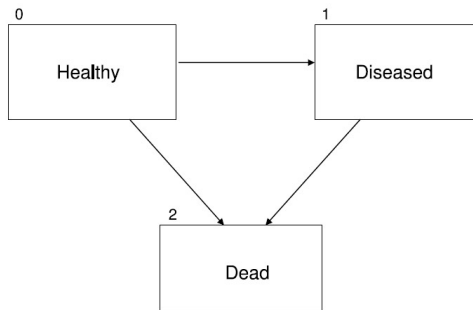
```
library(ggplot2)
```

```
ci.sim = Cuminc(time=obstime,status=h)
```

```
plot(x = ci.sim,use.ggplot = TRUE,conf.type = "log",lty =  
1:2,conf.int = 0.95)
```



# The illness-death model without recovery



**Fig. 3.19** *An illness-death model without recovery.*

The transition intensities  $\alpha_{01}(t)$ ,  $\alpha_{02}(t)$  and  $\alpha_{12}(t)$  give the instantaneous probability of transition from one state to another (where arrows show the possible transitions).

# Transition probabilities

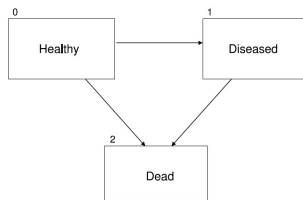


Fig. 3.19 An illness-death model without recovery.

$$P_{gh}(s, t) = P(\text{in state } h \text{ at time } t \mid \text{in state } g \text{ at time } s)$$

Then one may show

$$P_{00}(s, t) = \exp \left\{ - \int_s^t [\alpha_{01}(u) + \alpha_{02}(u)] du \right\}$$

$$P_{11}(s, t) = \exp \left\{ - \int_s^t \alpha_{12}(u) du \right\}$$

$$P_{01}(s, t) = \int_s^t P_{00}(s, u-) \alpha_{01}(u) P_{11}(u, t) du$$

# Transition probabilities

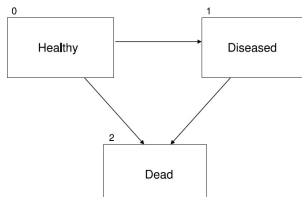


Fig. 3.19 An illness-death model without recovery.

$$P_{gh}(s, t) = P(\text{in state } h \text{ at time } t \mid \text{in state } g \text{ at time } s)$$

Further, one may show

$$P_{02}(s, t) = \int_s^t P_{00}(s, u-) \alpha_{02}(u) du + \int_s^t P_{01}(s, u-) \alpha_{12}(u) du$$

$$P_{12}(s, t) = 1 - P_{11}(s, t)$$

$$P_{22}(s, t) = 1$$

# Estimation of cumulative transition intensities

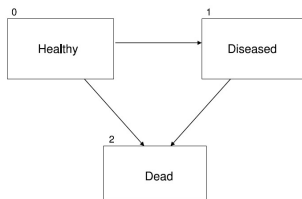
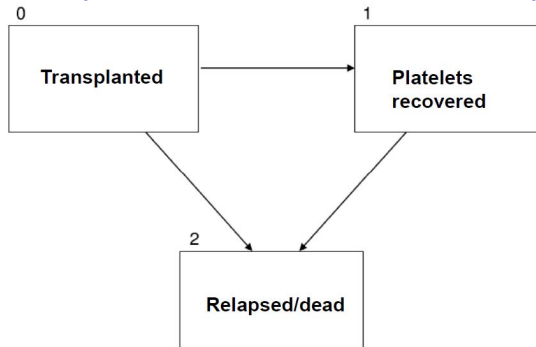


Fig. 3.19 An illness-death model without recovery.

Based on a sample from a population, we let  $N_{gh}(t)$ , for  $(g, h) = (0, 1), (0, 2), (1, 2)$ , count the number of observed transitions from state  $g$  to state  $h$  in  $[0, t]$ , and let  $Y_g(t)$  be the number of individuals in state  $g$  just prior to time  $t$ .

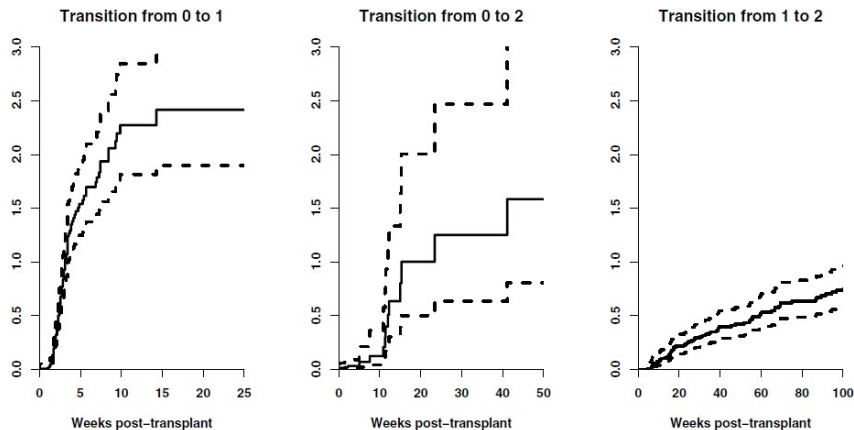
The intensity process of  $N_{gh}(t)$  takes the multiplicative form  $\lambda_{gh}(t) = \alpha_{gh}(t)Y_g(t)$ , so we may use the Nelson-Aalen estimator  $\hat{A}_{gh}(t)$  to estimate  $A_{gh}(t) = \int_0^t \alpha_{gh}(u)du$ .

## Example 3.16: Bone marrow transplantation



- ▶ Platelet recovery, relapse and death for bone marrow transplant patients.
- ▶ 137 patients with acute leukemia have had a bone marrow transplantation.
- ▶ The time of the events “platelet recovery” and “death/relapse” are recorded

## Example 3.16: Bone marrow transplantation. *Estimation of cumulative transition intensities*



**Fig. 3.20** Nelson-Aalen estimates with log-transformed 95% confidence intervals of the cumulative transition intensities for the bone marrow transplant patients. The states are 0: “transplanted,” 1: “platelet recovered,” and 2: “relapsed or dead.” Note that the time scale is not the same for the three estimates.



## Estimation of transition probabilities

$$\text{Recall: } P_{00}(s, t) = \exp \left\{ - \int_s^t [\alpha_{01}(u) + \alpha_{02}(u)] du \right\}$$

$$P_{11}(s, t) = \exp \left\{ - \int_s^t \alpha_{12}(u) du \right\}$$

$$P_{01}(s, t) = \int_s^t P_{00}(s, u) \alpha_{01}(u) P_{11}(u, t) du$$

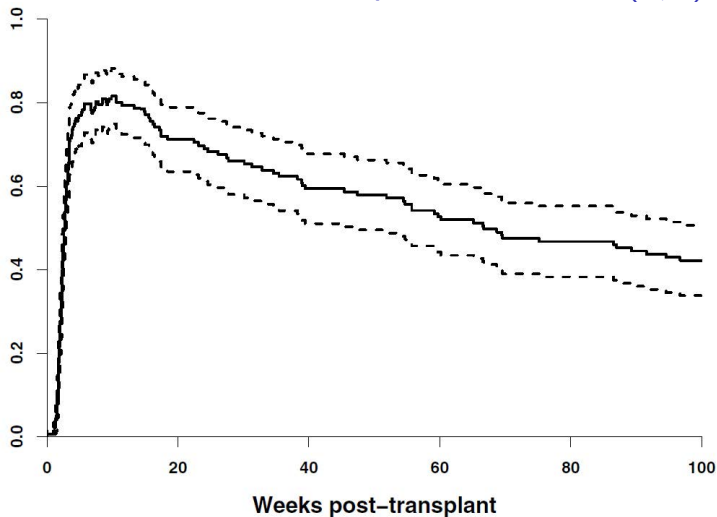
*This suggests the estimators:*

$$\hat{P}_{00}(s, t) = \prod_{s < T_j \leq t} \left( 1 - \frac{\Delta N_{0\bullet}(T_j)}{Y_0(T_j)} \right), \quad \text{where } N_{0\bullet}(t) = N_{01}(t) + N_{02}(t)$$

$$\hat{P}_{11}(s, t) = \prod_{s < T_j \leq t} \left( 1 - \frac{\Delta N_{12}(T_j)}{Y_1(T_j)} \right)$$

$$\hat{P}_{01}(s, t) = \sum_{s < T_j \leq t} \hat{P}_{00}(s, T_{j-1}) d\hat{A}_{01}(T_j) \hat{P}_{11}(T_j, t)$$

## Example 3.16: Bone marrow transplantation. *Estimation of transition probabilities $P_{01}(0, t)$*



**Fig. 3.21** Empirical probability of being in response function  $\widehat{P}_{01}(0, t)$  for the bone marrow transplant patients.

## A general Markov chain

Consider now a Markov chain  $X(t)$  with state space  $\mathcal{S} = \{0, 1, \dots, k\}$  with transition *probabilities*

$$P_{gh}(s, t) = P(X(t) = h \mid X(s) = g), \quad s < t, \quad g, h \in \mathcal{S}$$

and transition *intensities*

$$\alpha_{gh}(t) = \lim_{\Delta t \downarrow 0} \frac{1}{\Delta t} P(X(t + \Delta t) = h \mid X(t-) = g) \quad \text{for } g \neq h$$

Consider the transition probability matrix

$$\mathbf{P}(s, t) = \begin{pmatrix} P_{00}(s, t) & P_{01}(s, t) & \cdots & P_{0k}(s, t) \\ P_{10}(s, t) & P_{11}(s, t) & \cdots & P_{1k}(s, t) \\ \cdots & \cdots & \cdots & \cdots \\ P_{k0}(s, t) & P_{k1}(s, t) & \cdots & P_{kk}(s, t) \end{pmatrix}$$

*The key is to represent this matrix in terms of the transition intensities.*

# The Aalen-Johansen estimator

We have

$$\begin{aligned}P_{gh}(u, u + du) &= \alpha_{gh}(u)du; \quad g \neq h \\P_{gg}(u, u + du) &= 1 - \sum_{h \neq g} \alpha_{gh}(u)du\end{aligned}$$

It can be deduced from this that the matrix  $\mathbf{P}(s, t)$  can be represented as a matrix-valued product-integral

$$\mathbf{P}(s, t) = \prod_{s \leq u \leq t} (\mathbf{I} + d\mathbf{A}(u)) \quad (*)$$

where  $\mathbf{A}(t) = (A_{gh}(t))$  with  $A_{gh}(t) = \int_0^t \alpha_{gh}(u)du$  being the *cumulative* transition intensities.

The  $A_{gh}(t)$  are estimated by “ordinary” Nelson-Aalen estimators. and the  $\mathbf{P}(s, t)$  are then estimated by plugging in the Nelson-Aalen estimates in (\*). This corresponds to what we did in the special cases, and leads to the so-called *Aalen-Johansen* estimator.