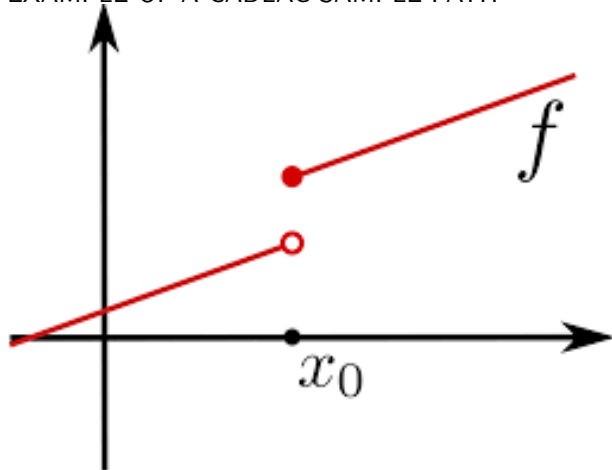


PROCESSES IN CONTINUOUS TIME

Key elements:

- ▶ $X = \{X(t) : t \in [0, \tau]\}$
- ▶ History (information) at time t is given by \mathcal{F}_t , with $\mathcal{F}_s \subset \mathcal{F}_t$ when $s < t$. Typically, \mathcal{F}_t corresponds to observation of $X(u)$ for $0 \leq u \leq t$
- ▶ $\{\mathcal{F}_t\}$ is called a *filtration*
- ▶ The process X is said to be *adapted* to $\{\mathcal{F}_t\}$ if $X(t) \in \mathcal{F}_t$ for all t .
- ▶ The process is called *cadlag* if its *paths* (trajectories on a graph) are right continuous with left hand limits

EXAMPLE OF A CADLAG SAMPLE PATH



MARTINGALES

IN CONTINUOUS TIME

$\mathcal{F}_s \subset \mathcal{F}_t$ whenever $s < t$

$M = \{M(t) : t \in [0, \tau]\}$

Definition:

$E(M(t)|\mathcal{F}_s) = M(s)$ for all $t > s$

IN DISCRETE TIME

$\mathcal{F}_1 \subset \mathcal{F}_2 \subset \mathcal{F}_3 \subset \dots$

$M = \{M_n : n = 0, 1, \dots\}$

Definition:

$E(M_n|\mathcal{F}_m) = M_m$ for all $n > m$

EQUIVALENT DEFINITIONS OF MARTINGALES

Discrete time:

$$E(\Delta M_n | \mathcal{F}_{n-1}) = E(M_n - M_{n-1} | \mathcal{F}_{n-1}) = 0$$

Continuous time:

$$E(dM(t) | \mathcal{F}_{t-}) = E(M((t + dt)-) - M(t-) | \mathcal{F}_{t-}) = 0$$

Here

- ▶ \mathcal{F}_{t-} is the history up to, but not including, time t .
- ▶ $dM(t)$ is the increment of $M(t)$ in the time interval $[t, t + dt)$, i.e.,

$$dM(t) = M((t + dt)-) - M(t-)$$

PREDICTABLE PROCESS

Discrete time: The process $H = \{H_n\}$ is *predictable* if the value of H_n is known at time H_{n-1} , i.e.

- ▶ $H_n \in \mathcal{F}_{n-1}$.

Continuous time: The process $H = \{H(t)\}$ is *predictable* if, informally, the value of $H(t)$ is known immediately before t . A sufficient condition for predictability of H is that it is

- ▶ adapted to \mathcal{F}_t
- ▶ has *left continuous* sample paths.

STOCHASTIC INTEGRALS

Discrete time: The transformation of martingale M by predictable H is

$$Z_n = H_1(M_1 - M_0) + H_2(M_2 - M_1) + \dots + H_n(M_n - M_{n-1}) = \sum_{i=1}^n H_i \Delta M_i$$

The process Z_n is a mean zero martingale.

Continuous time: The *stochastic integral* of a predictable process H with respect to a martingale M is

$$I(t) = \int_0^t H(s) dM(s) \stackrel{\text{def}}{=} \lim_{n \rightarrow \infty} \sum_{i=1}^n H_i \Delta M_i$$

Here the continuous processes H and M are approximated by discrete processes obtained by partitioning $(0, t]$ into n parts of length t/n and letting

► $H_i = H((i-1)t/n), \quad M_i = M(it/n)$

The stochastic integral $I(t)$ is a mean zero martingale.

THE DOOB-MEYER DECOMPOSITION

The *adapted* process $X = \{X(t) : t \in [0, \tau]\}$ is a *submartingale* if

$$E(X(t)|\mathcal{F}_s) \geq X(s) \text{ for all } t > s$$

Every increasing process – e.g. counting process – is a submartingale.

Doob-Meyer decomposition for submartingales:

$$X(t) = X^*(t) + M(t) \quad (\text{uniquely})$$

- ▶ X^* is an increasing *predictable* process, called the **compensator** of X
- ▶ M is a mean zero martingale

VARIATION PROCESSES IN DISCRETE TIME

The *predictable variation* process is defined by:

$$\langle M \rangle_n = \sum_{i=1}^n E\{(M_i - M_{i-1})^2 | \mathcal{F}_{i-1}\} = \sum_{i=1}^n \text{Var}(\Delta M_i | \mathcal{F}_{i-1})$$

The *optional variation* process is defined by:

$$[M]_n = \sum_{i=1}^n (M_i - M_{i-1})^2 = \sum_{i=1}^n (\Delta M_i)^2$$

Properties:

$$E(\langle M \rangle_n) = E([M]_n) = \text{Var}(M_n)$$

If H is predictable:

$$\begin{aligned}\langle H \bullet M \rangle &= H^2 \bullet \langle M \rangle \\ [H \bullet M] &= H^2 \bullet [M]\end{aligned}$$

VARIATION PROCESSES IN CONTINUOUS TIME

The *predictable variation* process is defined by:

$$\langle M \rangle (t) = \lim_{n \rightarrow \infty} \sum_{i=1}^n \text{Var}(\Delta M_i | \mathcal{F}_{(i-1)t/n})$$

where $[0, t]$ is partitioned into n parts of length t/n and $M_i = M(it/n)$.
Thus:

$$d \langle M \rangle (t) = \text{Var}(dM(t) | \mathcal{F}_{t-})$$

The *optional variation* process is defined by:

$$[M] (t) = \lim_{n \rightarrow \infty} \sum_{i=1}^n (\Delta M_i)^2 = \sum_{s \leq t} (M(s) - M(s-))^2$$

The last equality is valid for processes of finite variation (holds for our applications) and means the sum of squares of all jumps of $M(t)$.

VARIATION PROCESSES IN CONTINUOUS TIME (cont.)

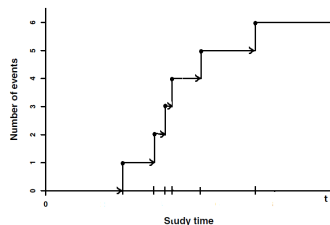
Properties:

$$E(\langle M \rangle (t)) = E([M](t)) = \text{Var}(M(t))$$

If H is predictable:

$$\begin{aligned} \left\langle \int H dM \right\rangle &= \int H^2 d \langle M \rangle \\ \left[\int H dM \right] &= \int H^2 d [M] \end{aligned}$$

COUNTING PROCESS BASICS



▶ $N(t) = \# \text{ events in } (0, t]$

▶ $dN(t) = \# \text{ events in } [t, t + dt) = \begin{cases} 1 & \text{if event at time } t \\ 0 & \text{if no event at time } t \end{cases}$

▶ **Intensity process** $\lambda(t)$ (*predictable*) is defined by:

$$P(dN(t) = 1 | \mathcal{F}_{t-}) \equiv P(\text{event in } [t, t + dt) | \mathcal{F}_{t-}) = \lambda(t)dt$$

Poisson process: $P(dN(t) = 1 | \mathcal{F}_{t-}) = P(dN(t) = 1) = \mathbf{deterministic} \lambda(t)dt$

Example of a random intensity: $P(dN(t) = 1 | \mathcal{F}_{t-}) = (N(t-) + \beta)\alpha(t)dt$
 $= \mathbf{random} \lambda(t)dt$