# Al over networks: <br> when decisions shall be taken together 

## Damiano Varagnolo

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Who am I?

## Purposes of this seminar

- discuss about some technological problems and potential solutions
- connect with you


## Purposes of this seminar

- discuss about some technological problems and potential solutions
- connect with you

> today's cut: divulgation

## Roadmap

- centralized vs. distributed
- how shall we share information?
- consensus
- taking decisions over networks


## centralized vs. distributed

What does centralized mean?

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What does distributed mean?

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What does distributed mean?


Different paradigms for different applications


## Summary of the pros and cons

logical simplicity vs. practical feasibility

main problems: what to exchange, and how

# how shall we share information? <br> (in the distributed paradigm case) 

Fixed vs. dynamic topologies


Wired vs. wireless communications


Synchronous vs. asynchronous communications


Lossless vs. lossy channels


## Summarizing, what are the main characteristics?

- do the connections change in time?
- what is the communication medium?
- is there a shared knowledge of time?
- may the communications fail?


## towards consensus: <br> the basic strategies for exchanging information

A fundamental strategy: gossip

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A fundamental strategy: gossip


Byzantine generals, and their problems


Broadcast communications


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Summarizing, how can we be robust?

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- broadcast
- asynchronous
- tolerating packet losses


## Summarizing, how can we be robust?

- broadcast
- asynchronous
- tolerating packet losses
remember: there is no free lunch!


## consensus

What does consensus mean?


Why is it important?


## Why is it important?


example of a collective decision: if in average colder than $18^{\circ}$, then turn the heaters on

## Average consensus

$$
\begin{cases}\text { local state: } & \theta_{i}, \quad i=1, \ldots, n  \tag{1}\\ \text { desired quantity: } & \frac{1}{n} \sum_{i=1}^{n} \theta_{i}\end{cases}
$$

## Max consensus

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\begin{cases}\text { local state: } & \theta_{i}, \quad i=1, \ldots, n  \tag{2}\\ \text { desired quantity: } & \max \left\{\theta_{1}, \ldots, \theta_{n}\right\}\end{cases}
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example of a collective decision: randomly select a leader

Max consensus: how?

## Order statistics consensus

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\begin{cases}\text { local state: } & \theta_{i}, \quad i=1, \ldots, n  \tag{3}\\ \text { desired quantities: } & \max \left\{\theta_{1}, \ldots, \theta_{n}\right\} \text { and } \min \left\{\theta_{1}, \ldots, \theta_{n}\right\}\end{cases}
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## Order statistics consensus

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example of a collective decision: rapid anonymous statistical counting

## Important remarks

max and order statistics consensus protocols can be broadcast, asynchronous, and using lossy media

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max and order statistics consensus protocols can be broadcast, asynchronous, and using lossy media
...but what about average consensus?

## small detour: <br> average consensus in practice

Gossip consensus

$$
\begin{gathered}
\left\{\begin{array}{l}
\boldsymbol{x}(k+1)=P(k) \boldsymbol{x}(k) \\
x_{i}(0)=\theta_{i}
\end{array}\right. \\
P(k)=\left[\begin{array}{cccccc}
1 / 2 & 0 & 0 & 1 / 2 & 0 & 0 \\
0 & 1 & 0 & 0 & 0 & 0 \\
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1 / 2 & 0 & 0 & 1 / 2 & 0 & 0 \\
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\end{gathered}
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Ratio consensus, i.e., how to use broadcast communications

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\end{array} \Longrightarrow z_{i}(k):=\frac{x_{i}(k)}{y_{i}(k)} \rightarrow \frac{\sum_{i} x_{i}(0)}{\sum_{i} y_{i}(0)}=\frac{1}{N} \sum_{i} \theta_{i}\right.
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Robust ratio consensus, i.e., how to handle lossy channels

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- $b_{i, x}$ : total cumulative mass of $x_{i}$
- $\beta_{i, x}^{(j)}: j$ 's local estimate of $b_{i, x}$

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taking decisions over networks

Numerical optimization: a hidden technology

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\begin{array}{ll}
x^{*}= & \arg \min _{x \in \mathcal{X}} J(x) \\
\text { s.t. } & A x=b  \tag{4}\\
& g(x) \geq 0
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## Centralized Newton Raphson



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From the centralized NR to its distributed version

Newton update:

$$
x^{+}=x-\frac{f^{\prime}(x)}{f^{\prime \prime}(x)}
$$

thus

$$
f(x)=\sum_{i=1}^{N} f_{i}(x) \Longrightarrow x^{+}=x-\frac{\sum_{i=1}^{N} f_{i}^{\prime}(x)}{\sum_{i=1}^{N} f_{i}^{\prime \prime}(x)}
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$$

i.e., parallel of two average consensi

## Example: distributed formation control



Example: distributed formation control
video
a look into the future

## TODOs

- more general \& robust distributed optimization procedures
- develop self-tuning procedures


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- more general \& robust distributed optimization procedures
- develop self-tuning procedures
- relieve humans from automatable burdens


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